

CORONA J

PERFORMANCE EVALUATION REPORT

MISSION 1044-1 and 1044-2

FTV 1639, J-41

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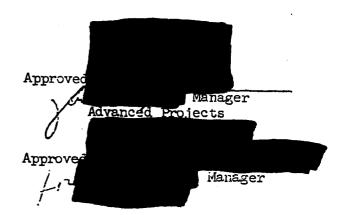


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INTRODUCTION

This report presents the final performance evaluation of Missions 1044-1 and 1044-2 of the Corona Program. The purpose of this report is to define the performance characteristics of the J-41 payload system and to identify the source of in-flight anomalies.

The performance evaluation was jointly conducted by representatives of Lockheed Missiles and Space Company (IMSC) and ITEK at the facilities of NPIC and AFSPPF. The off-line evaluation using Corona engineering photography acquired over the United States was performed at the individual contractors plants.

The quantitative data used for this report is obtained from government organizations. The diffuse density data, and MTF/AIM resolution are produced by AFSPPF. The vehicle attitude error values, frame correlation times are made at NPIC who also supply the Processing Summary reports published by

Computer programs developed by A/P are utilized to calculate and plot the frequency distribution of the various contributors to image smear to permit analysis and correlation of the conditions of photography to the information content and quality of the acquired pictures. Computer analysis of the exposure, processing and illumination data provides the necessary data to analyze the exposure criteria selected for the mission.

This report contains certain data summarized from Processing Summary, and from AFSPPF TERO Report,

SECTION 1

SYSTEM PERFORMALICE

A. MISSION OBJECTIVES

The payload section of Mission 1044, placed into orbit by Flight Test Vehicle #1639 and THORAD Booster #513, consisted of two panoramic cameras, two Stellar-Index cameras, two Mark 5A recovery capsules and a space structure to enclose the cameras and provide mounting surfaces for all equipment. Figure 1-1 presents an inboard profile of the J-41 payload system. This Corona "J" system is designed to acquire search and reconnaissance photography of selected areas of the earth from orbital altitudes. A seven day -1 mission and a seven day -2 mission was planned.

B. MISSION DESCRIPTION

The payload was launched from Vandenberg Air Force Base (VAFB) at 2131:19Z(1331:19 PST) on 2 November 1967. Ascent and injection were normal and the achieved orbit was within nominal tolerances. Tracking and command support was effected by the Air Force Satellite Control Facility consisting of tracking and command stations at

central control of the Satellite Test Center at Sunnyvale, California.

Mission 1044-1 consisted of a 6 day operation and was completed by air recovery on 8 November 1967. Mission 1044-2 was completed with an air recovery on 11 November 1967 following a 3 day photographic operation.

The very short -2 mission was precipitated by a potential failure in the lifeboat system.

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The comparison of the planned and actual orbit parameters is tabulated as follows:

ORBITAL PARAMETERS

Parameter	Predicted	Orbit 110 Actuals
Period (Min.)	90.1.7	90.333
Perigee (N.M.)	99.876	99.531
Apogee (N _• M _•)	223.750	219.940
Inclination (Deg.)	81.5	81.539
Perigee Latitude (Deg. N.)	19.24	33.816
Eccentricity	0.017191	0.01673

A single OAS rocket was fired on Rev 4, Rev 17, and Rev 113. These rocket firings produced the following results:

OAS ROCKET PERFORMANCE

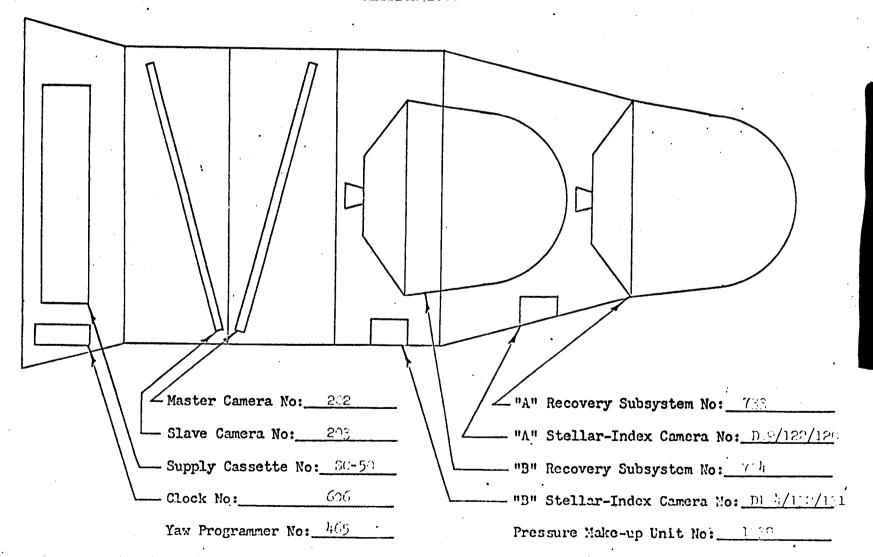
OAS Rocket	Velocity Gained
#1.	+ 16.2 FPS
#2	+ 15.7 FPS
<i>#</i> 3	+ 17.5 FPS

C. PANORAMIC CAMERAS

Both instruments operated satisfactorily throughout both missions, and produced good image quality except for minor bands of image smearing near the takeup and on many frames. The imagery was very sharp, and verified the validity of the new focus settings.

SCHEMATIC INBOARD PROFILE - CORONA J-41 SYSTEM

MISSION 1044



D. STELLAR-INDEX CAMERAS

Both the "A" and "B" S/I's operated satisfactorily and most Stellar images appear as points rather than the usual odd shaped stars.

E. OTHER SUB-SYSTEMS

The clock, instrumentation, pressure make-up, command and thermal control subsystems performed satisfactorily.

F. COMPONENT IDENTIFICATIONS AND SETTINGS

1. MASTER PANORAMIC CAMERA

a. COMPONENT ASSIGNMENT

Component	Serial Number
Main Camera	202
Main Camera Lens	2042435
Supply Horizon Camera	308-G6
Supply Horizon Camera Lens	12889
Take-up Horizon Camera	318-G5
Take-up Horizon Camera Lens	12886
Supply Cassette	SC-50
•	•

b. CAMERA DATA AND FLIGHT SETTINGS

Main Camera:

Lens	24"f/3.5
Slit Width	0,225"
Filter Type	Wratten 23A
Film Type	Eastman Type 3404

5.

Supply (Port) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/6.3

Exposure Time 1/100 second

Filter Type Wratten 25

Take-up (Starboard) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/8.0

Exposure Time 1/100 second

Filter Type Wratten 25

2. SLAVE PANORAMIC CAMERA

a. COMPONENT ASSIGNMENT

Component	Serial Number
Main Camera	203
Main Camera Lens	2162435
Supply Horizon Camera	299-G6
Supply Horizon Camera Lens	12903
Take-up Horizon Camera	297-G5
Take-up Horizon Camera Lens	12883
Supply Cassette	SC-50

b. CAMERA DATA AND FLIGHT SETTINGS

Main Camera:

Lens 24"f/3.5

Slit Width 0.175"

Filter Type Wratten 21

Film Type Eastman Type 3404

Supply (Starboard) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/8.0

Exposure Time 1/100 second

Filter Type Wratten 25

Take-up (Port) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/6.3

Exposure Time 1/100 second

Filter Type Wratten 25

3. MISSION 1044-1 STELLAR-INDEX CAMERA

a. COMPONENT ASSIGNMENT

Component	<u>Serial Number</u>
Camera	D-99
Index Reseau	122
Stellar Reseau	120

b. CAMERA DATA AND FLIGHT SETTINGS

Stellar Camera:

Lens 85 mm f/1.8

Exposure Time 1 second

Filter Type None

Film Type Eastman Type 3401

Index Camera:

Lens 38 mm f/4.5

Exposure Time 1/500 second

Filter Type Wratten 21

Film Type Eastman Type 3400

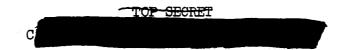
4. MISSION 1044-2 STELLAR-INDEX CAMERA

a. COMPONENT ASSIGNMENT

Film Type

	Component	Serial Number
	Camera	D-104
	Index Reseau	132
	Stellar Reseau	131
b •	CAMERA DATA AND FLIGHT SETTINGS	
	Stellar Camera:	
	Lens	85 mm f/1.8
	Exposure Time	l second
	Filter Type	None
	Film Type	Eastman Type 3401
	Index Camera:	•
	Lens	38 mm f/4.5
	Exposure Time	1/500 second
	Filter Type	Wratten 21

Eastman Type 3400



SECTION 2

PRE-FLIGHT SYSTE'S TESTS

As a standard procedure, the J payload systems are subjected to a series of tests which demonstrates a satisfactory level of confidence that the systems will indeed perform as required in their respective missions. The tests include and operational-type exposure to simulate thermal/altitude environment, a light-leak evaluation, and a dynamic measure of the photographic performance capabilities. Significant baseline levels and anomalies experienced with this system during the pre-flight testing are as follows:

A. ENVIRONMENTAL TEST

The J-41 payload system was subjected to an environmental HIVOS Chamber test from August 15 through August 19, 1966, and from August 27 through September 1, 1966. The interruption was caused by the actuation of a camera failsafe control during the cut and wrap sequence.

Except for some minor acceptable corona marking, the panoramic instruments performed satisfactorily. The Master camera failsafe was activated at the cut and wrap sequence when the film jammed in the felt seal preventing take-up into the "B" SRV. The failure was attributed to a combination of a misaligned "B" take-up cassette, and the vertical attitude of the camera system during the sequence which permitted the cut film to fall back and jam in the felt door opening.

The clock accuracy was satisfactory, except for one correlation that was outside of the accepted tolerance range.

The pressure make-up system operated normally. During PMU operate, internal pressure increased to 37-39 microns. Gas consumption was as high as 7.45 lbs/min.during -2 portion of the test.

The command system functioned properly for both bucket tests with no evidence of any equipment malfunctions.

B. RESOLUTION TEST

Initial resolution and theodolite tests were performed on 20 September 1966. Results of the thru-focus resolution tests of pan instruments 202 and 203 show the following characteristics:

Master Pan Instrument No. 202

Maximum high contrast resolution 175 lines/mm at -0.002 focal position.

Maximum low contrast resolution 115 lines/mm at -0.002 focal position

Slave Instrument No. 203

Maximum high contrast resolution 176 lines/mm at +0.001 focal position.

Maximum low contrast resolution 112 lines/mm at +0.001 focal position.

Additional Boston investigations indicated that optimum focus position would be attained by adding 0.002" shim to the scan head of the Slave instrument, and 0.001" shim to the Master instrument. The modified instruments were retested 22 October 1967, with the following results:

Master Pan Instrument No. 202

Maximum high contrast resolution 183 lines/mm at -0.0025 focal position.

Maximum low contrast resolution 120 lines/mm at -0.0020 focal position.

Slave Pan Instrument No. 203

Maximum high contrast resolution 185 lines/mm at -0.0015 focal position.

Maximum low contrast resolution 118 lines/mm at -0.0020 focal position.

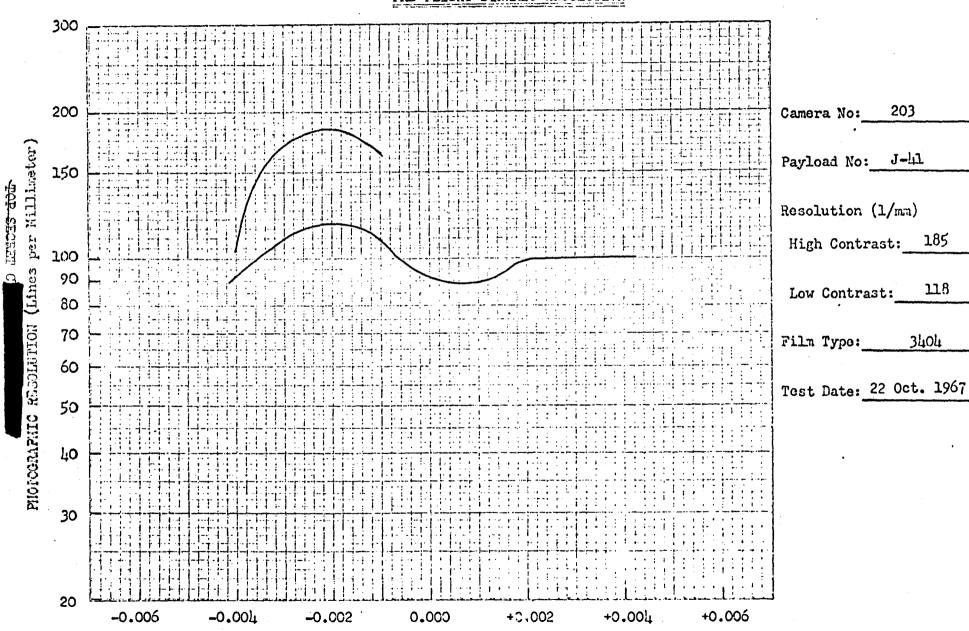
The final test data for both instruments is shown in Figures 2-1 and 2-2. Both instruments met the system requirements specification.

PRE-FLIGHT DYNAMIC RESOLUTION 300 200 Camera No: 202 150 Payload No: J-41 Resolution (1/mm) High Contrast: 183 100 90 80 Low Contrast: 120 PHOTOGRAPHIC ASSOLUTION 70 Film Type: 3404 60 Test Date: 22 Oct. 1967 50 40 30 20 -0.005 -0.004 -0.002 0.000 +0.002 +0.004 +0.006

FIGURE 2-1

THROUGH FOCUS INCREMENTS (Inches)

PRE-FLIGHT DYNAMIC RESOLUTION



THROUGH FOCUS INCREMENTS (Inches)

FIGURE 2-2

C. LIGHT LEAK TEST

The J-41 system was tested for light leaks on 12 August 1966, revealing major leaks at three of the four H.O. boot installations and at the Agena interface cover. Photomultiplier sensing techniques were used to verify the validity of repairs made.

D. FLIGHT LOADING AND CERTIFICATION

Loading of flight film was accomplished on 24 October 1967, and final pre-flight acceptance tests performed 25 October 1967. All functions were nominal, with no indications of light leaks or other sources of performance degradation.

SECTION 3

FLIGHT OPERATIONS

A. SUMMARY

Ascent through Agena ignition was nominal. The Agena engine "coughed" at approximately 128 seconds after Agena ignition and combustion chamber pressure was reduced during the last period of engine burn. The engine burned approximately 5 seconds longer than nominal. A hard engine shut-down was confirmed.

The achieved orbit parameters were low, but were within the three (3) sigma dispersions.

Both panoramic cameras operated satisfactorily throughout the flight.

Both Stellar/Index cameras operated satisfactorily throughout the flight.

The instrumentation system, clock system, and the yaw function generator performed normally for the duration of the flight.

An intermittent anomaly in the Lifeboat system developed in the -2 mission, with the possible initiation of an unplanned recovery sequence. As a result, the mission was intentionally terminated as early as possible.

Several commanding problems were encountered during this flight while commanding in the repetitive mode.

B. PANORAMIC CAMERA PERFORMANCE

Both panoramic cameras operated normally throughout the flight. Camera system dynamic operation, 99/101 clutch operation, start-up, shut-down, and film transport functions were normal on all monitored passes.

The cut and wrap operation and transfer to the -2 system occurred as programmed utilizing the KIK-ZORRO 38 command (early A to B switchover) on Rev 88.

The panoramic film was exhausted on Rev 140 frame No. 25 and frame No. 60 on the Master and Slave cameras respectively.

Panoramic Film Consumption

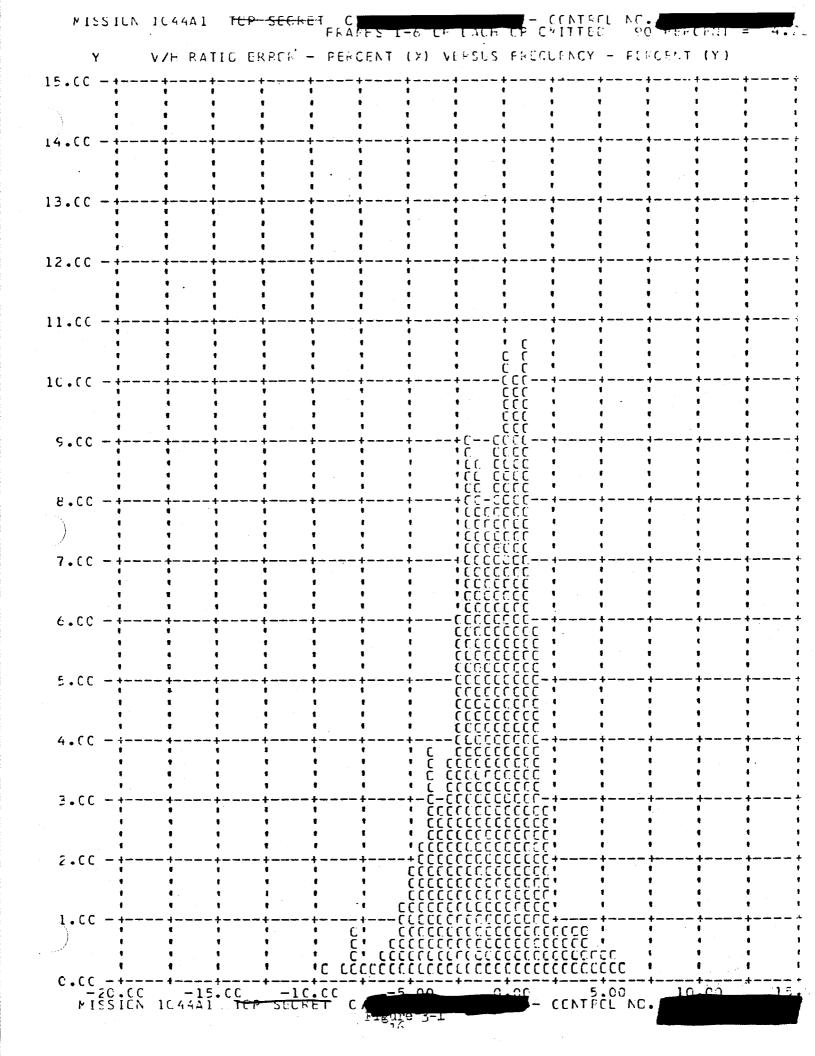
	Actual Frames	
	Master	Slave
Pre-Launch	137	137
-l Mission	2898	2880
-2 Mission	3011	3 030
Total	6046	6047

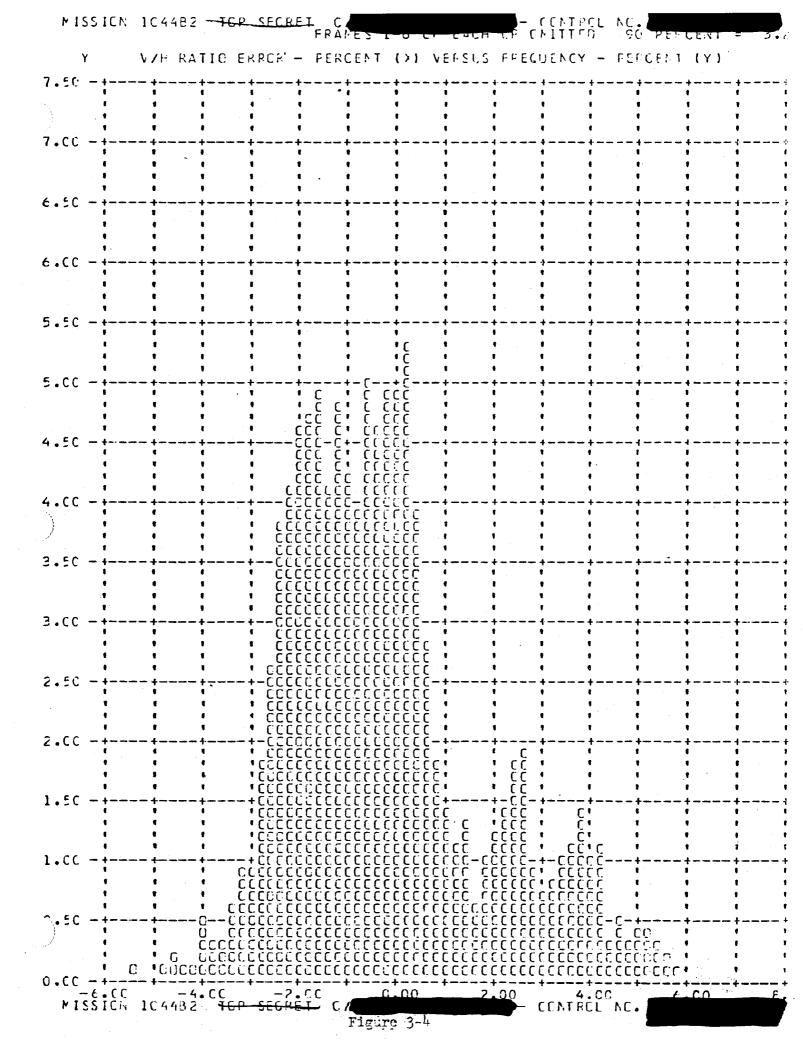
FMC Match

The V/H ramp to orbit match was acceptable throughout the flight. The following settings of RTC 6, 8, and 10 were utilized to obtain the optimum FMC match during the flight.

	RTC	Comm	ands	REMARKS
	<u>6</u>	<u>8</u>	10	
RTC Positions	7	4	6	Launch thru Rev 3
	7	2	9	Rev 4 thru Rev 12
	6	3	9	Rev 13 thru Rev 16
	7	3	9	Rev 17 thru Rev 44
	8	2	. 8	Rev 45 thru Rev 65
	7	3	9	Rev 66 thru Rev 75
	8	2	9	Rev 76 thru Rev 91
	7	3	9	Rev 92 thru Rev 114
	7	3	10	Rev 115 thru the end of the mission

However, the design of the 1000-series ramp programmer limits this optimum FMC match to a nominal band of latitude defining areas of primary interest. The extensive operations over a wide range of latitude experienced in this mission (Ref. Figs. 5-5 to 5-10) increases the statistical deviation, as is evident in Figures 3-1 through 3-4.





C. STELLAR/INDEX CAMERA PERFORMANCE

Both the -1 and -2 Stellar/Index cameras operated satisfactorily on all monitored engineering passes. Telemetry data indicated the programmer, metering functions, and shutter monitors performed satisfactorily.

D. INSTRUMENTATION AND COMMAND SYSTEM PERFORMANCE

The instrumentation system performed normally throughout the total mission.

The command system performance was satisfactory for both missions.

However, numerous command anomalies were encountered during the mission when real time commanding (RTC) was performed in the repetitive mode.

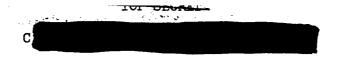
Analysis indicated that the RTC commands issued at the

showed erratic command duration times. It was recommended that the command generation equipment be verified for proper operation.

One RTC 9 was missed on Rev 56 while transmitting in the repetitive mode. The A/P stepper also failed to advance on two correctional commands and a third command was required to place the A/P stepper in the proper position. Analysis indicates that the stepper failed to respond to the issued command. A specific cause of this anomaly could not be determined from the available data. However, this command box was checked prior to shipment for proper command response time to command durations of 65 milliseconds and the system functioned normally.

E. CLOCK SYSTEM PERFORMANCE

The clock system operation was normal for the entire mission. Satisfactory time correlation between the flight clock and the was obtained. The ratio of clock time to system time was 1:00000026563.



F. PRESSURE MAKE-UP SYSTEM PERFORMANCE

The pressure make-up system performance was normal for the duration of the mission. Average gas consumption was approximately 8.4Δ PSI/min for the 240 minutes of total operate time. The system had a reserve of 620 PSI at the end of the flight.

G. THERMAL ENVIRONMENT

The thermal control pattern on this payload system was modified prior to launch to produce a thermal environment of $75 - 10^{\circ}$ F.

Temperature data from the acquisitions are included in Tables 3-1 and 3-2. The average instrument temperatures ranged from a high of 85°F. and 86°F. to low of 68°F. and 68°F. on the Master and Slave instruments respectively.

H. YAW PROGRAMMER

The vehicle Yaw Programming functioned properly throughout the mission. However, because of pre-flight programming error which placed the function start pulse approximately 800 seconds late, the Yaw attitude achieved was approximately 55 Degrees out of phase with the desired profile. A more complete description of this function and its effect on mission performance is presented in Sections 4, 7 and 8.

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I. RECOVERY SYSTEM

An early switchover from the A to the B Recovery systems was performed on Pass 88, with all functions appearing normal. The 1044-1 recovery capsule was successfully recovered by air-catch on Rev 97 at 1608 PST on 9 November 1967. Capsule impact was approximately 50 N.M. south of the predicted impact. All available data has been analyzed and all functions appeared to have occurred normally. All re-entry events appeared normal and close to the predictions except for deceleration chute deployment which occurred 0.12 seconds late.

	Latitude	Longitude				
Predicted	25° 56.4° N	165° 51.08° W				
Actual	25° 06° N	165° 42' W				

The intermittent failure of a relay in the "Lifeboat" system electronics during the 1044-2 mission resulted in several cases of inadvertent lifeboat timer starts as well as one case of power being applied to the primary recovery system. Because of the possibility of an uncontrolled recovery, the 1044-2 mission was terminated early. The 1044-2 recovery capsule was successfully recovered by air-catch on Rev 144 at 1509 PST on 11 November 1967. All re-entry events appeared normal and close to the predictions except for parachute cover off which occurred 1.97 seconds early. Capsule impact was close to nominal.

	<u> Latitude</u>	Longitude				
Predicted	21° 0.56' N	154° 28.1' W				
Actual	21° 5.0' N	154° 33.0° W				

J. RADIATION DOSAGE

Each recovery system flown on a Corona mission contains a sealed packet of Eastman Type 3401 and Royal X Pan emulsions to determine the total radiation received at the take-up cassette. Both film types have been irradiated by IMSC at various levels and the base plus fog densities recorded after controlled processing.

Following recovery the film dosimeter packets are removed at A/P and processed with a pre-flight sample of the same film type and sensitometric control film. The resulting base plus fog density measurement of the dosimeter strips is used to ascertain the total radiation level. The table below presents the base plus fog readings for the dosimeter strips and the radiation level equivalents.

	Missi	on 1044-1	Missi	on 1044-2
Emulsion	B + F Density	Radiation	B + F Density	Radiation
			bensity	
Type 3401	0.22	0.9 R	0.25	1.3 R
Royal X Pan	0.27	0.5 R	0.30	0.6 R

These levels are below that which will degrade the photography.

SECTION 4

PHOTOGRAPHIC PERFORMANCE

A minimum of payload system photographic anomalies occurred during Missions 1044-1 and 1044-2, thus providing one of the most trouble-free flights to date. The image sharpness attained was considered equal to any previous Corona J-1 photography, permitting most imagery to be viewed at 60 x magnification. The overall image quality was judged to be generally good where not degraded by atmospheric attenuation; however, there was a predominance of cloud cover over the highest priority targets.

A. PANORAMIC INSTRUMENTS

The Master Camera produced 2898 frames (8049 feet) of photography during Mission 1044-1, and 3011 frames (7951 feet) during Mission 1044-2. The Slave camera produced 2880 frames (8009 feet) during Mission 1044-1, and 3030 frames (7963 feet) during Mission 1044-2. The quality of the photography produced by the two cameras was very similar, and was rated comparable to Mission 1035. The MIP Frames were rated 85.

The array of fixed resolution targets at Holloman AFB, New Mexico, were recorded during Mission 1044-2. The average system resolution of these targets was judged to be approximately eight feet for both instruments.

Both instruments exhibited characteristic anomalies, most objectionable of which was an appreciable build-up of emulsion particles. This condition was apparently accentuated by the very long operate times commanied during Mission 1044-2 so as to facilitate an early recovery. However, there appeared to be no significant reduction in information content because of this condition.

All auxiliary data recording functions operated normally throughout the flight, with the exception of missing binary data blocks on six occasions randomly over the missions. (Four occasions were on the forward camera, two on the aft). In each instance all of the other auxiliary data was present. This behavior was observed in pre-flight altitude testing, but was not considered detrimental so corrective action was waived.

The quality of the photography was adequate to readily identify intermittent bands of smearing near the takeup end of format caused by film flutter as the scan head enters the photographic format area. This anomaly is characteristic of instrument operation, and should be reduced considerably with the CR concepts.

It must be noted that this system was the first of the 1000-series to have the revised focus settings for a more precise compensation of the vacuum focal shift characteristics of the lenses used. Although there are many factors influencing the photographic quality achieved, it is reasonable to assume that the desirable performance of Mission 1044 verifies the validity of the new peak focus positions.

B. STELLAR/INDEX CAMERAS

The Stellar/Index film recovered consisted of 449 frames of photography from each film path of S/I D99/122/120 (Mission 1044-1), and 464 frames from each path of S/I D104/132/131 (Mission 1044-2). The cameras operated normally throughout the respective mission. There were 15 to 30 or more stellar images detectable on most frames despite a level of flare which affected approximately 50 percent of each frame. Most of the stellar images were good, and were point-type images. There was an appearance of Corona static marking occurring intermittently throughout the Mission 1044-2 stellar record.

The index cameras produced good quality imagery through each of the respective missions. The reseaus were sharp and well defined in both instruments. Several instances of dendritic static were recorded on the preflight, postflight and the last eight frames of the Mission 1044-2 index film.

C. OBSERVED DATA

Detailed evaluation of the engineering materials available at A/P indicated that the smearing effects from the V/h and yaw steering errors (see Section 8) did indeed create a detectable limitation to system performance in many instances in the mission. As predicted in the smear analysis, frames obtained with a large yaw steering error show a distinct disparity in quality between the forward and aft photography directly related to the difference in their exposure times.

When the ground smear contributions drop below some apparent threshold value (estimated to be approximately five feet for this system) on both instruments, the resulting forward and aft photography becomes very comparable and very good in quality. The Holloman AFB targets photographed during Pass 126 indicated approximately eight feet ground resolution for both instruments with a calculated theoretical smear of about $\frac{1}{2}$ feet (which corresponds to a theoretical ground resolution limitation of $\frac{1}{2}$ feet). In comparison, Pass 63 photography had noticeable disparity between forward and aft performance corresponding to relatively high smear values for the forward looking imagery (approximately $\frac{1}{2}$ feet theoretical smear induced ground resolution limitation).

The mission processing summary indicated a major disparity in original negative development in several instances throughout the mission. Evaluation of engineering pass 125 indicated that the aft-looking record, which was processed at the primary development level, had a significant loss of detail and image quality when compared with the corresponding forward-looking photography which was processed at the full level. There was excellent cloud highlight definition in the aft photography, but the important ground and culture imagery was suppressed to the extent of a distinct loss in information content.

D. PERFORMANCE MEASUREMENTS

A summary of MTF/ATM resolution values measured by SPPF is tabulated below. The microdensitometer slit used was 1 micron by 80 microns.

Mission	Camera	Cycles/mm	Avg	Ground Resolution
1044-1	Fwd	78	70	151
1044-2	Fwd	61	70	15'
1044-1	Aft	71	7 0	10l#
1044-2	Aft*	84	78	132'

*Samples from portion processed by dual gamma method

The details of the measurement and computing techniciques, targets measured and target locations are fully reported in the evaluation report published by AFSPPF and are not included in this report. These values were determined by using the "Interim MTF/AIM Program" technique.

It should be noted that the value shown for 1044-2 Fwd camera includes one reading of only 32 cycles/mm. The reading may be accurate, but does not represent the nominal level of system performance. In comparison, visual resolution targets recorded ten passes after this reading location indicated an effective ground resolution of approximately eight feet, which corresponds to an MTF reading on the order of 130 cycles/mm.

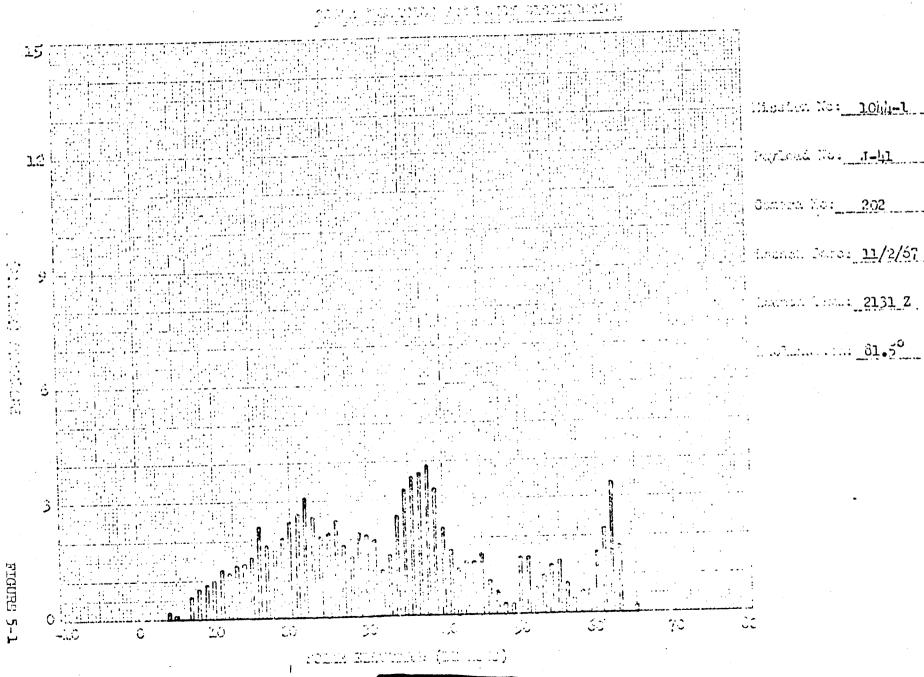
SECTION 5

PANORAMIC CAMERA EXPOSURE

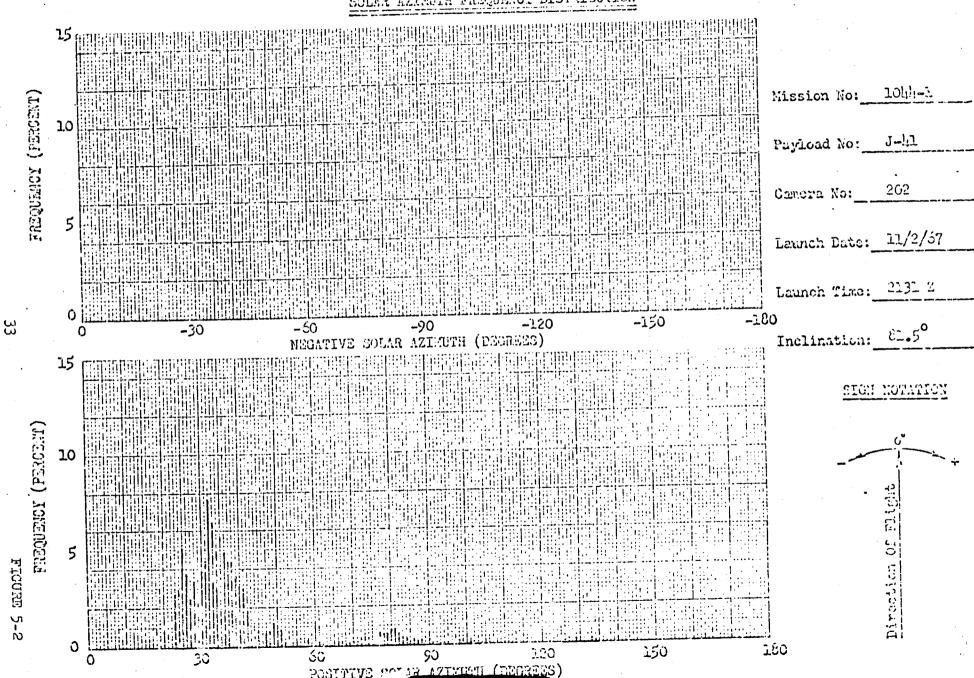
The Master camera contained a 0.200 inch slit and a Wratten 23A filter. The Slave camera had a 0.150 inch slit and a Wratten 21 filter. These conditions placed the nominal exposure between the full and the intermediate processing curve.

The frequency distributions of the solar elevations and solar azimuths encountered during the photographic operations are shown in Figures 5-1 to 5-4.

The rominal exposure times of the Master and Slave cameras are shown as a function of latitude for passes D-25, D-70, and D-116 in Figures 5-5 to 5-10. Superimposed on these plots are relative distributions of camera operations for the portion of the mission represented by each plot. These distributions became very uniform with latitude as the mission progressed because of the extended operations programmed in order to reduce mission duration.



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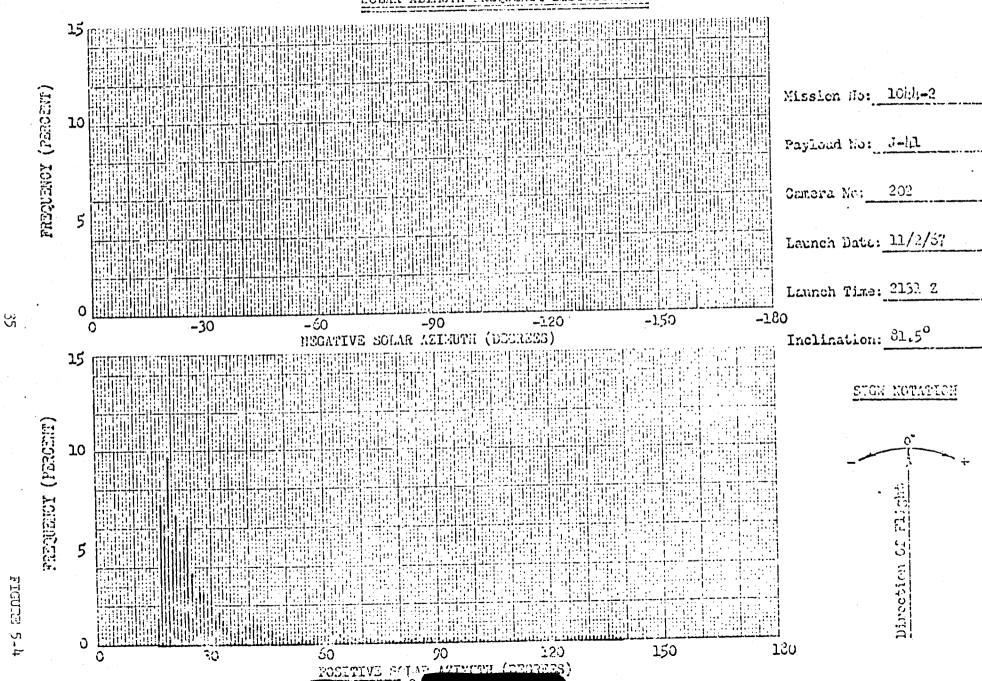
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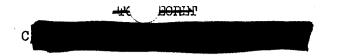
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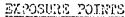
FIGURE 5-3

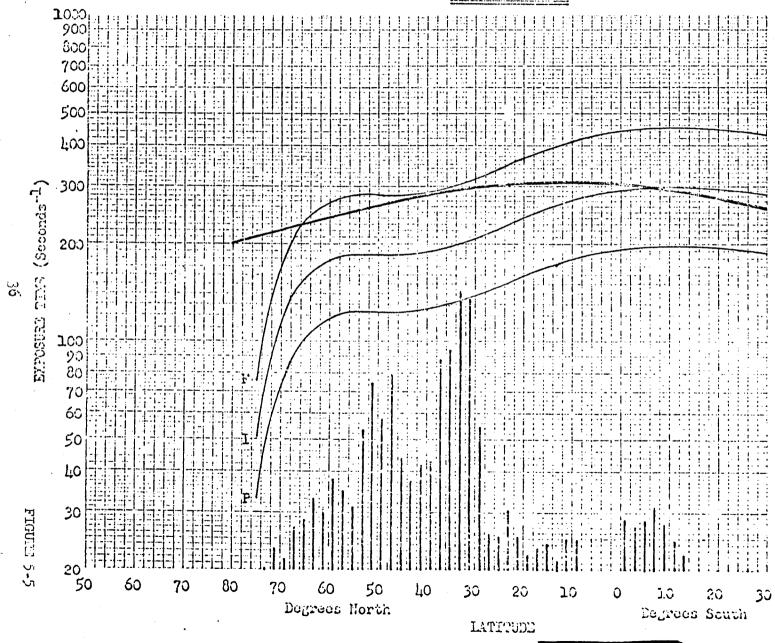


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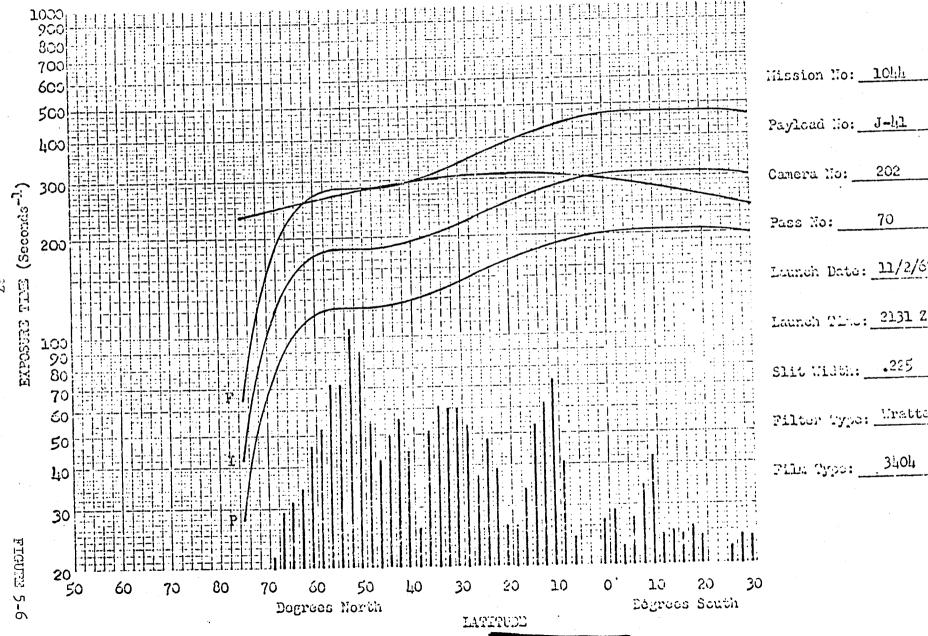






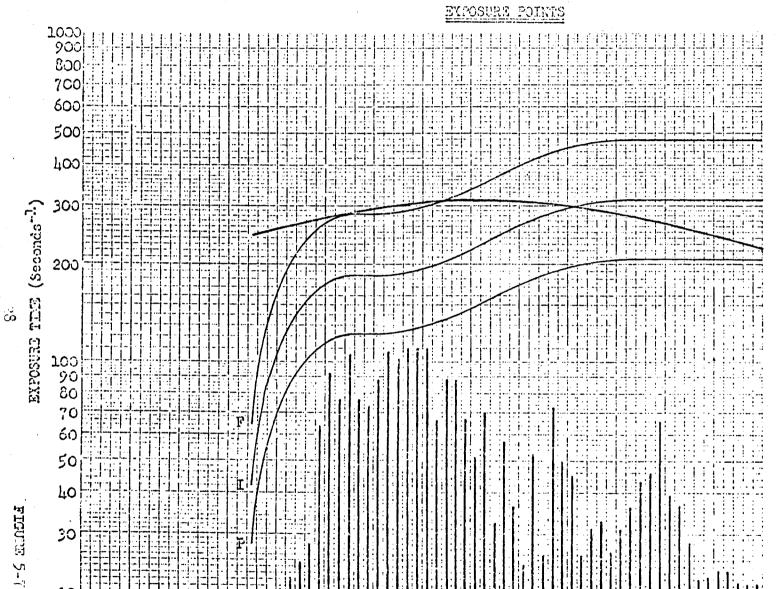
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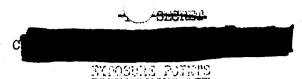
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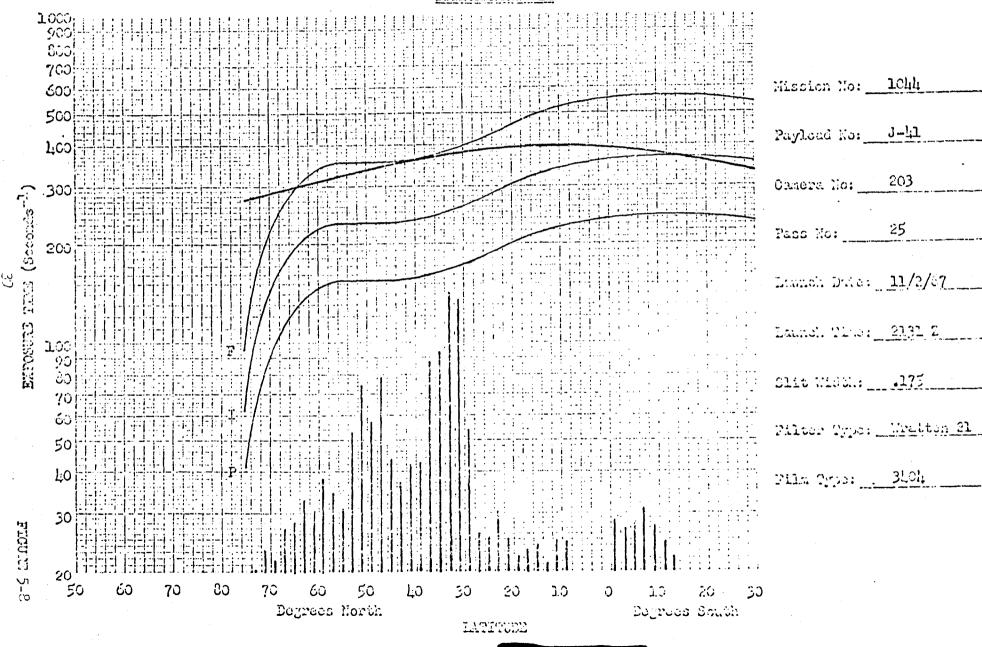
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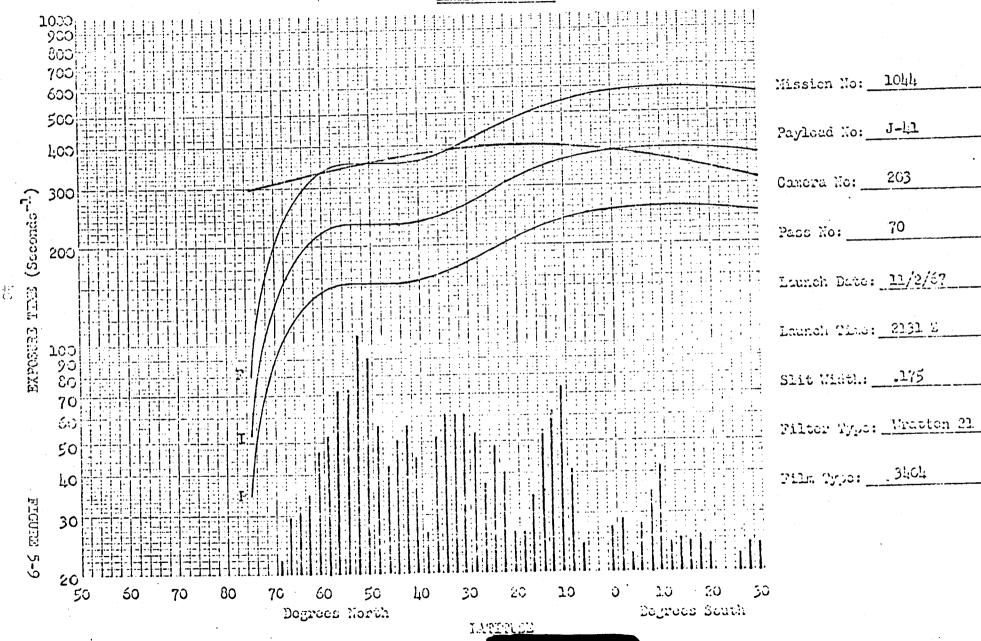
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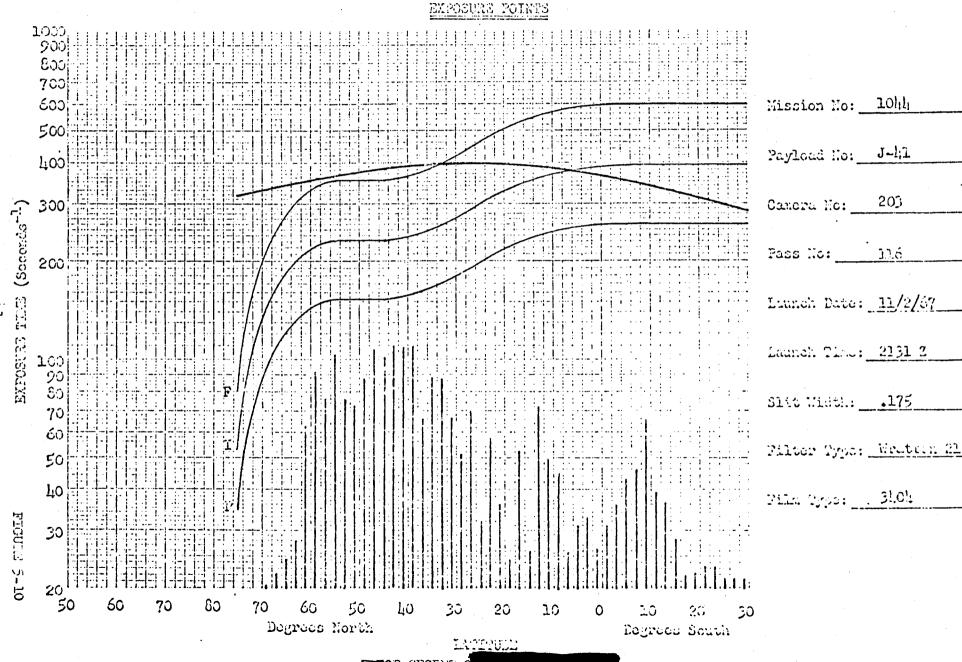








C. SHORDT



SECTION 6 DIFFUSE DENSITY LEASURE-CENTS

The diffuse density measurements made by AFSPPF were computer sorted at A/P to permit analysis of the density ranges resulting from the three levels of conventional processing and from the dual gamma process experiment. The sorting technique utilizes the base plus for density values for the conventionally processed materials where measurements up to 0.09 density are considered as having received Primary processing, 0.10 to 0.17 as Intermediate, and above 0.17 density as Full. The percentage of this material that was processed at each level, based on the computer sort, is tabulated below with the predicted and reported processing percentages.

Mission	Camera		Primary	Intermediate	<u>Full</u>	Transition
1044-1	Fwd	Predicted Reported Computed	0 0 0	13 6 8	87 88 92	6
10դր-1	Aft	Predicted Reported Computed	0 2 0	19 12 23	81 71 77	- 15 -
1044-2	Fwd	Predicted Reported Computed	4 0 0	16 4 7	80 92 93	<u>_</u>
1044-2	Aft	Predicted Reported Computed	8 5 0	24 17 28	68 63 72	- 15 -

Approximately 30 percent of the total mission original negative was subjected to a "dual-gamma" processing experiment. The results indicate a very effective reduction in the maximum cloud and snow densities with only minor influence in the normal range of terrain densities.

Graphical computer plots of the sampled density distributions are presented in Appendix A, Pages A-1 through A-48. Note the variation between the conventional processing plots and those for the dual gamma process. The differences in the cloud Dmax are very distinct. There is, however, a more subtle distinction that should be emphasized; namely, the incidence of lower terrain Dmin densities with the dual gamma process than with conventional processing. The reasons for these variations are obvious upon comparison of the corresponding sensitometric curves, Figures 6-2 through 6-13.

The sensitometric curves also illustrate the distinct deviations of the actual flight material processing from the standards and from the R-2 day samples. Obviously, there is need to maintain exposure control based on actual effective processed film speeds rather than on the standards. This will be especially true for the dual gamma process if future deviations continue to be as significant as was experienced in this case. As the dual gamma process becomes operational, it is anticipated that reliable processing controls will be attained. Likewise, it is anticipated that as additional progress in target density analysis is made a corresponding reliable exposure criteria will become a reality.

A surmary of the processing and exposure analysis for the conventionally processed material is shown in Table 6-1. The terrain D-Min criteria, (range) for proper exposure and processing is 0.40 to 0.90 density units. The area measured for D-Min is selected subjectively and is not necessarily the obsolute D-Min in the photography.

The terrain D-Min criteria has been found to be an implequate indicator of optimum target exposure. Maximum intelligence is derived from specific target densities meeting this criteria; which, in general, results in overall terrain D-Min values repeatedly below the 0.40 density level. It is therefore apparent that the more desirable missions will, most likely, be reported as significantly underexposed by the present terrain D-Min criteria.

A density range chart, Figure 6-1, is included in this report. This type of chart for Missions 1004 to 1031 is included in the A/P final report for Mission 1031.

These charts are produced from the same density measurements previously mentioned in this section. The computer produced the mean, median and range figures for the various processing levels used. The chart includes the number of frames (samples) in which the density measurements were made. These measurements are made on approximately every tenth frame throughout the mission. It should be noted that the density figures shown for Missions 1044-1 and 1044-2 include both dual-gamma and conventionally processed materials, thus tending to artificially enlarge the apparent range of densities, especially for the cloud D-Max values.

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F 1551UN 1044-1	INS	TR - AFT	1/16/68	PROCESSI	NO AND EXPO	SURE ANALYSIS
PROCESS S LEVEL	AMPLE S17E	UNDER EXPCSED	UNDER PROCESSED	CCRRECT EXP&PRCC	OVER PROCESSED	OVER EXPOSED
PRIMARY INTERMEDIATE FULL ALL LEVELS	0 37 126 163	C PC C PC 28 PC 21 PC	0 PC 11 PC 0 PC 2 PC	0 PC 65 PC 65 PC 65 PC	19 PC 19 PC 7 PC 10 PC	19 PC 5 PC 0 PC 1 PC
MISSION 1044-2	INS	TR - FAC	1/16/68	PROCESSI	NG AND EXPO	SURE ANALYSIS
PROCESS S LEVEL	AMPLE SIZE	UNDER FXPCSED	UNDER PROCESSED	TOBRRECT CORRESPECT	OVEP PRCCESSED	OVER EXPOSED
PRIMARY INTERMEDIATE FULL ALL LEVELS	C 12 168 160	0 PC 0 PC 38 PC 36 PC	0 PC 0 PC 0 PC 0 PC	0 PC 42 PC 58 PC 57 PC	7 PC 58 PC 4 PC 7 PC	7 PC 0 PC 0 PC 0 PC
#1881UN 1044-2	182	STR - AFT	1/16/69	PRLCESS1	NG AND EXPO	SURE ANALYSIS
PROCESS S	AMPLE SIZE	UNDER EXPLSED	PRECESSED.	CORRECT EXPERCE	PRCCESSED.	OVER EXPUSED
PRIMARY INTERMEDIATE FULL ALL LEVELS	0 46 116 162	0 PC C PC 31 PC 22 PC	0 PC 25 PC 0 PC 7 PC	0 PC 59 PC 66 PC 64 PC	24 PC 15 PC 3 PC 6 PC	24 PC 0 PC 0 PC 0 PC
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TABLE 6-1

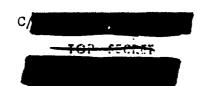
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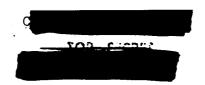
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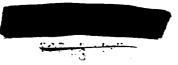
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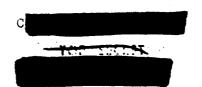
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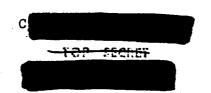
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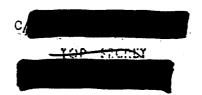


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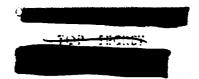


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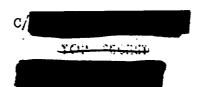


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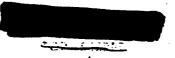


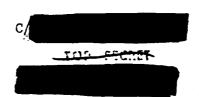


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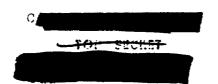
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SECTION 7

VEHICLE ATTITUDE

The vehicle attitude errors for both Mission 1044-1 and 1044-2 were derived from the reduction of the Stellar camera photography.

This attitude data is supplied to A/P by NPIC.

The attitude errors for each frame and the attitude control rates are calculated at the A/P computer facility. The computer also plots the frequency distribution of the rates and errors. Figures 7-2 through 7-7 show these distributions for Mission 1044-1 and Figures 7-8 through 7-13 for Mission 1044-2.

The summary table below lists the maximum attitude errors and rates that were experienced during 90 percent of the FWD camera photographic operations, excluding the first six frames of each operation, and the total range of the errors and rates.

	Missi	Miss	sion 1044-2	
<u>Value</u>	90%	Range	90%	Range
Pitch Error (°)	0.30	-0.35 to + 0.02	0.37	-0.62 to + 0.10
Roll Error (°)	0.15	-0.28 to + 0.46	0.37	-0.57 to + 0.06
Yaw Error (°)	3.42	-1.20 to + 3.80	3.31	-0.40 to + 3.60
Pitch Fate (0/hr.)	14.53	-85 to +85	23.64	-65 to +75
Roll Rate (0/hr.)	26.23	-58 to +76	30.62	-85 to +50
Yau Rate (0/hr.)	51.28	-98 to +24	29.78	-80 to +10

The yaw angle error represents the difference between the actual vehicle yaw attitude and the ideal yaw angle that would provide correct ground image motion. Because of a pre-flight programming error in the

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placement of the function start position, the yaw programmer was approximately 800 seconds out of phase with the desired performance. The large yaw angle error indicated reflects this condition. Figure 7-1 graphically depicts these relationships. The effects on image quality are discussed in Sections 4 and 8.

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Figure 7-7

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SECTION 8 IMAGE SMEAR ANALYSIS

The frame correlation tape supplied to A/P by NPIC contains the binary time word of each frame of photography. A computer program has been assembled at A/P which calculates the exposure time of each frame and compares the camera cycle rate with the ephemeris to calculate the V/h mismatch (Section 3), which is then combined with the vehicle attitude error and rate values of each frame and the crab error caused by earth rotation at the latitude of each frame. The program outputs the net IMC error and the total along track and cross track limit of ground resolution that can be acquired by a camera regardless of focal length and system capabilities.

The computer rejects the first six frames of all operations as the large V/n error induced by camera start-up is not representative of the overall system operations. The frequency distribution of the TMC errors and resolution limits are computer plotted and are shown in Figures 8-1 through 8-12.

The surmary table 8-1 presents the maximum IMC errors and resolution limits that existed during 90% of the photographic operations and the total range of values during all operations that were computed.

The relatively high values obtained in Mission 1044 reflect the combined effects of imperfect V/h and yaw steering matching as discussed in Sections 3 and 7. The apparent discrepancy in resolution limit values between the forward and aft-looking instruments is, in reality, a dramatic illustration of the relative influence of the difference in exposure time when coupled with smear contributing V/h and attitude errors.

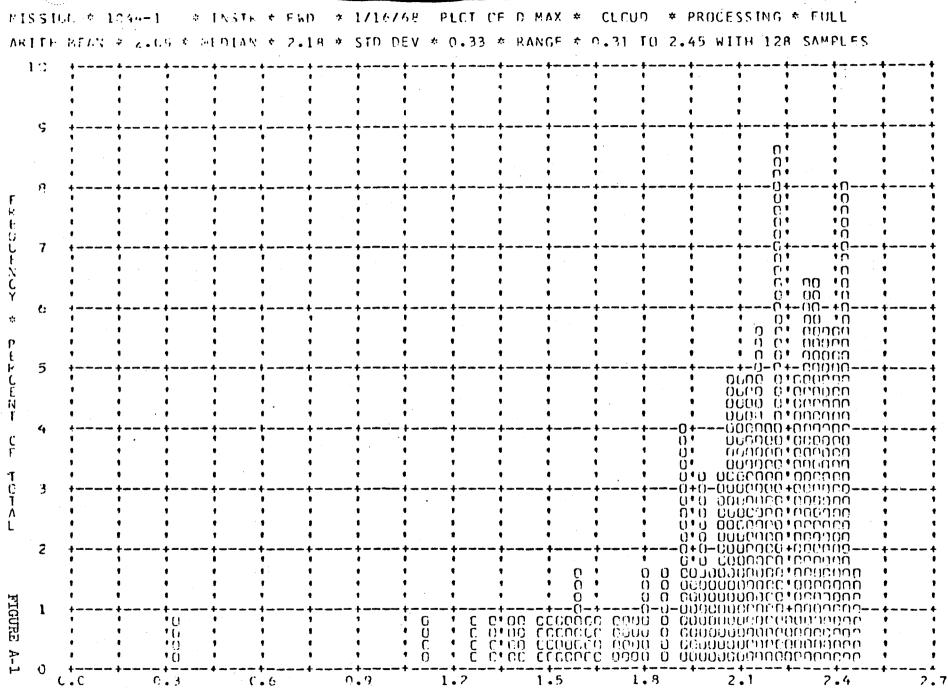
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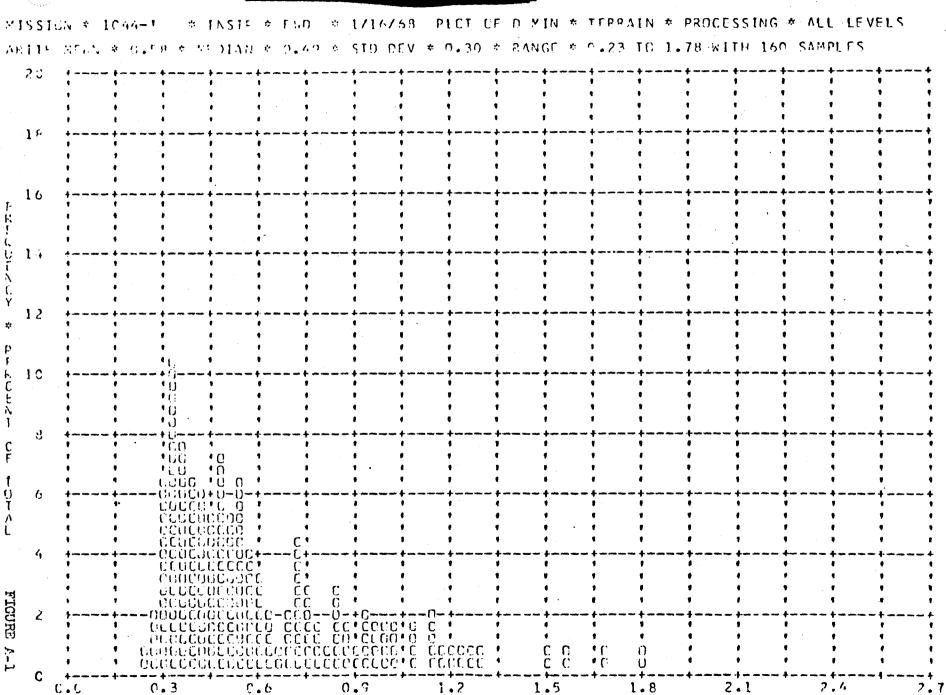
MISSION 1044

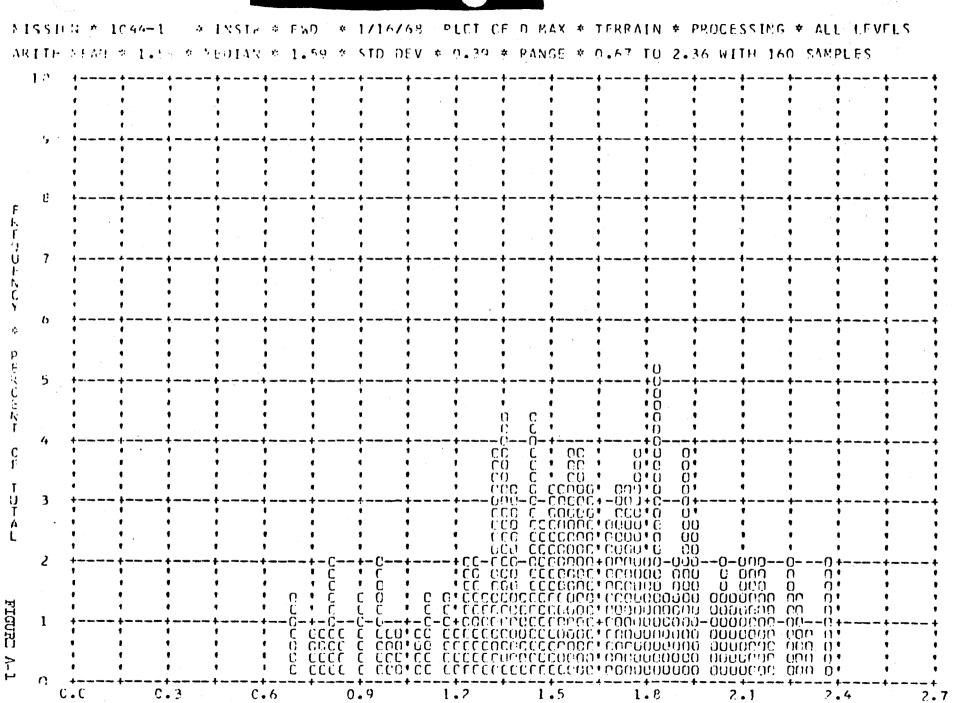
IMC RATIO AND RESOLUTION LIMITS

VALUE	UNITS	CAMERA	MISS: 90%	ION 1044-1 RANGE	MISSI 90%	ON 1044-2 RANGE
IMC Ratio Error	%	FWD	4.55	-9.5 to +5.5	3.21	-5.4 to +6.0
		AFT	4.06	-10.0 to +6.5	3.26	-5.6 to +6.2
Along Track Resolution Limit	Feet	FWD	6.98	0.2 to 13.6	4.38	0.2 to 8.8
		AFT	4.36	0.2 to 9.8	3.25	0.2 to 6.6
Cross Track Resolution Limit	Feet	FWD	9.75	0.2 to 11.0	8.39	0.2 to 10.4
		AFT	6.19	0.2 to 7.6	5.30	0.2 to 6.0

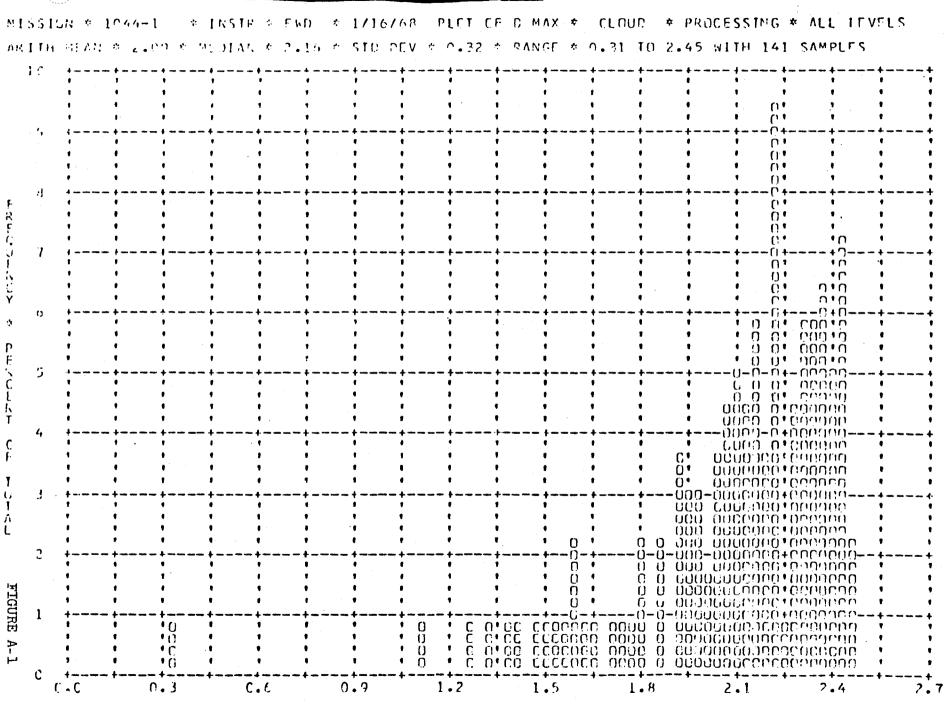
TABLE 8-1

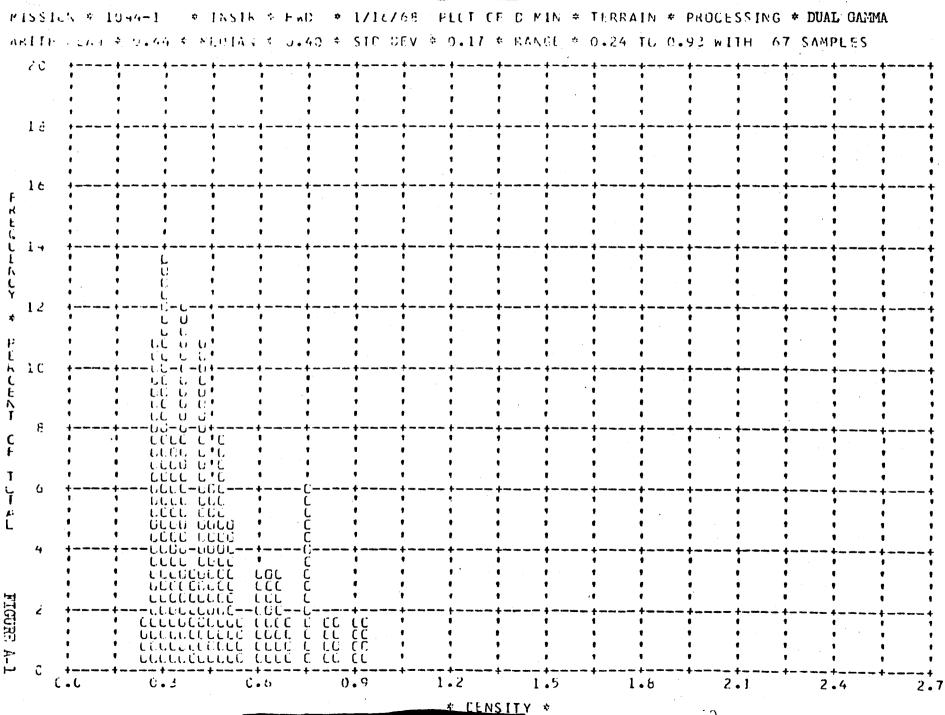




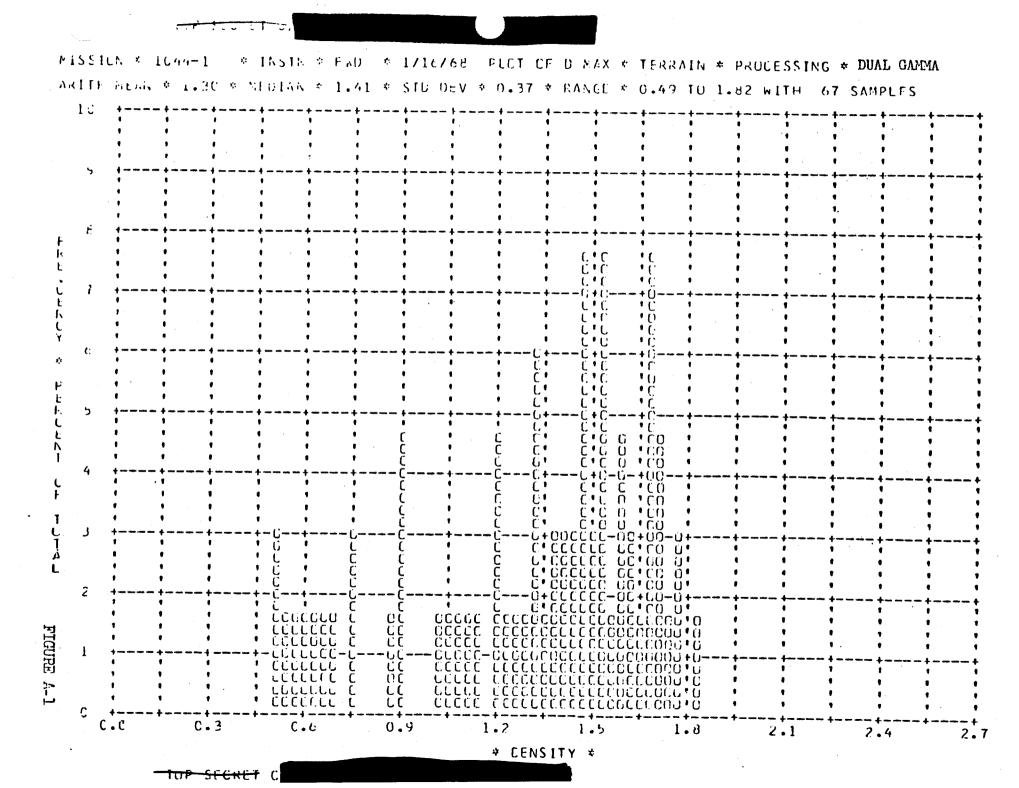


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SECTION 9

SYSTEM RELIABILITY

Reliability calculations for the payload are based on a sample beginning with M-7. Hence both the major part of the Mural program and the "J" program are covered in the calculation. For certain auxiliaries, i.e., the stellar-index camera and the horizon cameras, the sample size is changed to recognize incorporation of modified equipment or new designs where reliability was one of the principal reasons for the modification. However, for primary mission function, the sample size is consistent with reliability reporting for the vehicle.

The reliability estimates of this section deal exclusively with the payload. Failures to achieve orbit or vehicle induced failures are thereby excluded. Recoveries before a complete mission has been completed are considered as full missions providing that early termination was caused by reasons not connected with payload operation. Film quality is not considered in the reliability estimate calculation. Hence, only electrical and machanical functioning are considered.

The reliability estimate is also divided into primary and secondary functions. The primary functions are operation of the panoramic cameras, main camera door operation, operation of the payload clock, and recovery operations. The secondary mission functions are horizon camera operation excluding catastrophic open shutter failure mode, auxiliary data recording, and stellar-index camera operation. A summary of estimated reliability is shown in Table 9-1.

Fanoramic Camera Reliability

Sample Size - 195 opportunities to operate.

Two failures - S/I Programmer on System J-19

Film Transport on System J-42

Assume - 3000 cycles per camera per mission.

Estimated Reliability = 98.6 at 50% confidence level

Main Camera Door Reliability

Sample Size - 62 vehicles x 3 doors = 124 opportunities to operate Estimated Reliability = 99.5 at 50% confidence level.

Payload Command and Control

Sample Size - 11,424 hours operation in sample Two failures

Estimated Reliability = 96.1% at 50% confidence level

Payload Clock Reliability

Semple Size - 11,424 hours operation in sample No failures

Estimated Reliability - 99.0% at 50% confidence level

Estimated Reliability of Payload Functioning on orbit = 96.5% at 50% confidence level

Recovery System Reliability

89 opportunities to recover

1 failure - improper separation due to water seal - cutter failure Estimated Reliability - 98.25 at 50% confidence level Stellar-Index Camera Reliability

Sample begins with J5 (Does not include DISIC units in 1100 series systems)

Sample size = 28,480 cycles

Four failures

Estimated Reliability = 93.3% at 50% confidence level.

Horizon Camera Reliability

Sample begins with J5 - 115,000

Estimated Reliability of Single Camera - 99.1% at 50% confidence level

Estimated Reliability of Four Horizon Cameras at a Parallel Redundant System = 99.9% at 50% confidence level.

ESTIMATED RELIABILITY SUMMARY

(AT 50% CONFIDENCE LEVEL)

Г						AMIRA	.RY FU	NCTIONS				SECONDARY	FUNCTIONS
		PANGR	AASIC	PARIORA	HIG CAMENA	,		PAYLGAS	;	TIERO - NO	RECOVERY	STELLAR - INDEX	HORIZON
1	:"S\$10H	CANE			CRCO		YSTEM	CLOCK		FUNGTIONS	SYSTEM	CALERAS	CALLERAS
	NUMBER	SAMPLE		SAMPLE		SAMPLE		SAMPLE			SAMPLE	SAUPLE	SA):PLE
1		FAILUI	RE3	11	AILURES	FAI	ILURES	PAILUNES		RELIABILITY	FAIL URES	FAILURES	FAILURES
L			LIAFLITY		ACLIABILITY]	AELIADILITY	net.	IABILITY		RILLIADILITY	RELIABILITY	TELIASTIT!
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1	9038 10 1008	1			· · · · · ·		0	0		96.1	F-1 -	3	
-{			97.3		99 C		98.0		98.0		90.7	63.1	91.
[C4 _		54		3216		3216			20	4250	15,000
-	1009	16,	•	سستا	<u> </u>	1	<u> </u>	0	اـ	96.2]	
1	1007	<u> </u>	97.4		90.7	i	98.0	ا	53.0	00.12	91,3	69.3	·
}-		- =				 					\ <u>-</u>	·	
1		co		156		3432		3432			22	5100	18,000
-	1010	1			0		0	·		96.4	1	3	0
L		1	97.6	<u> </u>	- 53.3	1	90.1	<u> </u>	90.1		92.5	73.7	94.
1		172		28		3600		3600			24	5525	21,000
1	1011				0		0	0		96.8		0' _	 0 -
		l	97.7		93 9		1.03		98.1		93.0	91.7	95.
\vdash	······································	76				3/20	مستسسن	3720	=		26	5525	24.000
	. 1012	100		60	0	37.50	0 _	0		96.9	100	0 _	24,000
ļ	. 1012					Γ.		· -		. 30.3	1 200		· · · · · · · · · · · · · · · · · · ·
-		ļ	97.8		90.9		90.2		90.2		93.5	!	95.
		78		62		3940		3940			28	5950	25,500
1	1013	-			0		·	0		96.0			0
L		I	97.6		99.0		95.9		\$8.3		94.0	95.1	96.
Г		82		64		4056		4056			30	6375	28,500
-	1014	1			- a		1	0		96.1		 	- 0
1		l	97.9	<u> </u>	99.0		93.1		98.3		94.4	69.6	96.
H		86		66		4320		4320	-		32	7225	31,500
1	1015			100	<u> </u>	1320	•	0		96.1	,	1	0
1	1013		98.0		99.0		96.3		98.4	30.1	94.6	90.4	36.
-			30.0		35.0		30.3		30.4		 	<u> </u>	
1		90		68		4560		4560			34	7650	34,500
1	1016				0		·	0_		96.4	<u> </u>	<u> </u>	°
ı.		l	98.1	<u> </u>	99.0		96.5		93.5		95.8	31.0	97.0
	٠.	94		70		4760		4760 ·			36	0925	37,500
l	1017	10	ســ ۱۹	ļ			·	0		97.6			0 _
1		·	99.3	.	99.0		96.7		90.6		95.4	92.3	97.3
-								4920			30	8980	
j		98		72		4920	•	1320			36	6960	40,500
ı	1018				.0	•	<u> </u>	' -	-003	96.7	95.6	1	
<u> </u>			98.3		99.1		96.8		98.7				97.5
j		102		74		5136		5136			39	8075**	43,500
	1019				0		1	0		96.8			0
1			98.4	1	99.1	<u> </u>	96.9		38.7		95.8	91.5	97.6

<u>.</u>

ESTIMATED RELIABILITY SUMMARY

(AT 50% CONFIDENCE LEVEL)

•			PRIMARY F	INCTIONS			. SECONDARY	FUNCTIONS
м:55:0н	PANORAMIC CAMERA	PANORAMIC CAMERA DOORS SAMPLE	COMMAND B CONTROL	SLOCK	ON - ORBIT FUNCTIONS	REGOVERY SYSTEM	STELLAR - INDEX CAMERAS	HORIZON CAMERAS
KUMBER	FAILURES	FAILURES	FAILURES	SAMPLE FAILURES RELIASILITY	RELIADILITY	FAILURES RELIADILITY	SAMPLE FAILURES RELIABILITY	SAMPLE FAIL URES RELIABILITY
	RELIABILITY		RELIABILITY				# T	
1026	108	78	5544	0 0	96.9	43 96.1	2 69.9	48,000 0 97.
	98.5	76	5376	53.76		41	9830	46,500
1021	98.5	0 99.1	97.0	0 78.8	96.9	96.0	2	97.
1022	112	80	5784	5784	96.9	45	11,550	51,000
1022	99.5	99.2	97.3			96.3		- ::
1023	114		6000	6000	96.2	1		54,000
·	90.6		+			96.5	<u></u>	
1024	118	84	6240	6240	96.3		2	57,000
	98.6	99.2	96.0	98.9		96.6	13,890	<u> </u>
1025			2	0	96.4		2	0
	98.6	99.2	6720	6720		53	14,740	63,000
1026	98 7	0 99.2	2 96.3	0 99.0	•96.5	96.8	92.6	0 98
1027	128	90	6744	6744	36.5	55	15,165	64,500
	98.7	<u> </u>	+	+ : <u> </u>		97.0		
1028	132	92	6960	6960	96.7	97.1	3	67,500
	98.7	99.2	7200	7200		59	30.7 	70,500
1029	98.6	99.3	2 96.5	099.1	96.8	97.1	68.7	
1030	140	96 0	7440	74.0	96.9	61	17,430	73,500
	98.9	-	96.6			97.2	69 3	98.
1031	143	98		7704	96.9	63	18,280	76,500

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(AT 50% CONFIDENCE LEVEL)

				UNGTIONS			SECONDARY	FUNCTIONS
FICSION NUMBER	PANGAAMC GAMEAA	25:33	COMMAND & CONTROL 2 SYSTEM		ON - ORBIT FUNCTIONS	RECOVERY SYSTEM	STELLAR - INDEX CAMERAS	nesizen Camenas
	Sample FAILURES FILABLETY	SEMPLE FAILURES - HOLIZO LITY	FAILURES	SAMME FAILUMES MELIAGILITY	RELIABILITY	FAILURES	SAMPLE FAILURES KELIANJITY	SAMPLE FAILURES
:033	47 50.5	100	•	7968	57.1	65		79,500
.034	151		16 à	0200		67	19,960	62,5C0
	98.9	99.3	90.9		97.2	97.5) 9,
.035	55.0	:	2	نک ن 99.2	97.~	97.6	4	68,500
1030	50	104	8520 2	8523	97.3	69		85,500 0
. 1037	163	ice	97.0	5048		97.6	22,530	91,500
	99.0	99.4	97.2	99.3	97.4	57.7	51.6	
1C38	99.0	0	2	. 0	97.5	,	23,360 4 91.9	94,500
:039	99.0	0 ,	2	9600	97.5	77	24,230	97,500
1040	176	0	9840	9840 C	97.5	79	25,040	100,500
	99.0		10,176	99.3		97.9	92.4	_
	99.1	99.4			97.6	97.9	7	c بن
,042	99.1		2	0 99.4	97.7	95.0	1	0 0
1043	187			10,898	97.2	1 s	27,630	000,000
 		<u> </u>	97.71	59,4		29.0	53.1	J:

(AT 50% CONFIDENCE LEVEL)

			FRISLARY FO	INSTIGUE			SECCHDARY	FUNCTIONS
Lucion Admits	223.3 (A110 23.7 (A1	AMAMMA CAMAN L BOUND	A COMPANO A CONTROL LI MONER) PAMICAS () 0,000	on - gadit Functions	RECAYINY SYSTEM	STELLAD - MOEX	HCATCH COMMAN
1		FA CUITS	Factoris	FAILUACS	RELIADILITY	1 SAMPLE	FAILURES MILLER LITY	2-1:4:1:
1.01	3.00		-11,600	11,10.	. # # 96.5	95.1	12,565	1112.000
1044	1136	0	61 2 50.1	11,454 0 93.0	96.5	The second second second	146,400	110,000
							53.3	
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DIRIC REPLACES SAI CAMERAS ON 1100 SERIES SYSTEMS

WW CALCULATIONS ADJUSTED TO NOMINAL 14-DAY MISSION STANDARD

SECTION 10

SUMMARY DATA

The comparison of the operating parameters and the performance achieved by previous missions has been difficult due to the large volume of data that results from each mission. Some of the pertinent characteristics from prior missions have been summarized in Tables 10-1 through 10-3.

The summary data was started with Mission 1004 as the J-05 comera system was the first to incorporate the major modifications of the titanium drum and scan arm, four roller scan head and Corona J capabilities. Only those missions that culminated in the recovery of some photography have been listed, therefore Missions 1003, 1005 and 1032 are deleted.

THE CHARMS (CA)

MISSION SUMMARY

	<u> </u>	<u> </u>	T	<u> </u>	OHEIT		GER		VAS	LEH CVV			VE CAM		STELLAR-INDEX
MISSION NUMBER	PAYLCAD A 11. A	VEHICLE NUMBER	LAUNCH DATE	LAU'ICH TIME	Inclination	ALTITUDE (NM)	LOCATION (*N)	RECOVERY PASS	CAMERA NUMBER	SE 11	FILTER TYPE	CAMERA NUMBER	SL11 (-)	FILTER TYPE	CAMERA NUMBER
100-	J-05	1174	2/15/64	2138 Z	74 9	99.9	29.0	49 :12	124	0.250	W-21	125	0.250	W-21	029/29/29
1006	1-00	1176	6/4/64	2259 Z	79 9	84.0	63.2	65 120	148	0 500	W-21	149	0.200	W-21	045/47/45
1007	J-07	1609	C/19/64	2318 2	85.0	99.2	41.5	65 128	114	0 250	W·25	145	0.200	W-21	D43/43/43
ಚನಿಕ	J-10	1177	7/10/64	2314 2	85 0	99 4	40.8	49 112	150	0 200	W-21	151	0.200	W-21	048/45/48
1000	J-12	1605	8/5/64	2316 ₹	80 1	99.6	39.5	49 128	154	0.200	W-21	155	0.200	W-21	033/28/3
1010	J-11	1178	9/14/64	2254 7	84.9	97.4	42.5	65	152	0 175	W-21	153	0.175	W - 21	038/30/3
1011]							65							030/36/30
	3X	1170	10/5/64	2150 2	79.9	99.3	20.9		1	0.175	W-21	161	0.175	W-21	057/57/5
1012	J-13	1179	10/17/64	2202 \$	75.0	96.2	32.4	49 81	156	0.200	W-21	157	0.200	W-21	051/51/47
1013	J-15	1173	11/2/64	5120 S	80.0	.100.0	25.0	65 81	158	0.225	W-21	159	0.225	W-21	D52/49/55
:0.4	J-16	1160	11/.9/64	2036 2	70.0	103.2	65.6	3: 145	162	0.250	W · 25	139	0.175	W-21	D53/59/49 D50/44/4
1015	J-17	1607	12/19/64	2110 2	74.9	96.7	21.5	01 175	138	0.250	W-25	141	0.175	W-21	DG1/61/61
1016	J-16	IEOB	17:5765	2101 7	74.9	99.4	30.2	81 159	132	0.250	W-25	133	0.175	W-21	058/58/5
1017	J-14	1611	2/25/65	2144 Z	75.0	97.2	25.9	81 145	140	0.250	W-25	165	0.175	W-21	021/21/21
1013	J-19	1012	3/25/65	2111 2	96.0	100.2	40.3	66	122	0.250	W-25	123	0.175	W-21	D20/20/20 D20/20/20
1019	J-04	1614	4/29/05	2144 2	85.0	99.1	27.1	80	118	0.250	l		l		022/22/2
								97	 	ļ	W-25	119	0.175	W-21	019/18/1
1020	J-20	1613	6/9/65	2158 Z	75.1	97.1	40.6	113	136	0.250	W-25	137	0.175	W-21	002/05/69
1021	J-21	1615	5/10/65	1803 Z	75.0	109.2	24.3	81 161	166	0.175	W-21	167	0.250	W-25	063/69/69 025/27/2
1022	J-22	1617	7/19/65	2201 Z	85.0	99.7	30.3	65 144	168	0.250	W-25	169	0.175	W-21	D65/77/70 D24/24/24
1023	J-23	1618	6/17/65	2100 Z	70.0	97.8	29.0	81 144	170	0 225	W-25	171	0 150	W-21	D17/19/02 C66/75/72
IC24	J-24	1619	9/22/65	2131 Z	80.0	95.9	18.4	81 161	172	0 225	W-25	173	0.150	W-21	009/72/84
IC25	JX-28	1616	10/5/65	1746 2	75.0	112.9	44.3	81	142	0.175	W-21	127	0.175	W-21	073/78/68
1026	J-25	1620	10/28/65	2117 2	75.0	93.0	17.0	(6)	174	 	W-25	175	 	 -	075/92/93
1027	JX-27	1621					<u> </u>	17	 	0.225			0.150	W-21	072/89/85
			12/9/65	2110 2	80.0	97.4	17.3	33	164	0.250	W-25	163	0.175	W-21	D77/S1/97 DG8/74/83
1028	J-26	1610	12/24/65	2106 5	80.0	97.6	28.4	144	176	0.250	₩-25	177	0.175	W-21	074/76/95
															MECIJON

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MISSION SUMMARY

				,	i in?		27.		1 82.5	3.65	51 6A	51.4	96 - CA9	TRA	STELLAR-INDEX
	i yay taa		Launin	LAUNCH TIVE	INCLUATION (*)	ALTTURE	LOSALICA	RECOVERY PASS	CAMERA NUMBER	SEIT	F1(1)2	CAMERA NUMBER	SLIT	FILTER	CAMERA NUMBER
29	J-27	- K.M., it	2/2/06	2:32 2	75.:	99.5	22 5	81 163	1	0.275		179	0.175	W - 21	079/94/51 070/70/9
ا نیا د)ورز	1. <u>—</u>	1622	3/9/66	2262.2	75 0	97 b	16.7	01_1.3	102	0.275	W-25	193	0.175	W-21	094/100/107 002/198/10
.54)	i	.527	4/7/66	2202.2	75 1	l 104.5	23 3	113	164	0 225	W-23A	195	0.150	W-21	083/101/89
	V+20	'خست. آ منت الالالالا	:	! ()	i					0 150	W - 21	;81	0.150	W-21	001/07/101
	د د د د	13	5/24/66	6213 2	, 001	102.0	60.7	62 176	194	0 200	W - 21	195	0.200	W-21	D01/105/109 D34/102/7
5:4		1926	6/2//36	2131 2		105 4	18 2	81	190	0 200	W-23A	137	0 150	W-21	G65/109/7G
illi illi illi illi illi Salahti		i e e e e e e e e e e e e e e e e e e e	1	2:14 /		99 5	29.1	المسترانا	 	0.225	W-23A	:69	0 175	W-21	[095/127/13 [30/034]
.035			875763	2040 /	; .65 c	102.4	22.9	110 2.2	1 193		W-23A	191	0 150	W-1:1	500 M O M
		12:2	11/6/66		156 0	9. 6	14.5	16 197	150	0.225	<u> </u>	96:	Č 175	W-21	piowawas
.036	; = 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	16.29	' 4767	l i i i i i i i i i i i i i i i i i i i	i	56 9	29 2	ы ы	1 :52	0 225	W-23A	193	0.175	W-21	353/06/112
	;	, 	2/22/6/	2.02 3	60 0	970	30.2	10 - 177	206	10 225		207	0.175	W-21	0103/131/132
	J-25	1030	3/33/67	1856 2	85.1	99.7	26.3	145	196)	0.175	W-21	:97	0.225		078/95/00
: 34:	3.45	.634	5/9/57	2152 2	1 36.1	100.1	33.5	93 215	308	0.225	W-23A	209	0.:75	W-21	3105/134/103
10.2		1633	6/16/67	2135 2	0.ca	96 S	29.1	57 240	204	3 200	W-23A	205	Ů.150	W-21	097/120/117 098/121/
1043	J12	1537	8/7/57	2144 2	1 au.0	162.1	16.3	113	200	6.200	W-23A	261	0.150	W-21	10:07/135/135
	 			j		[.	1 97 240	302	*	W-21	303	*	W-23A	0151C NO 3
1101	CH-1	1641	9/15/67	13412	80.0	84.6	5.7	97 208		.	Ŵ·23.		·	W - 2:	099/135/150
1644	J-41	: :639 	. 11/2/67	213; 2	81.5	93.9	15.4	199	202	0.225	W-23A	203	0.175	W-21	5.047.327
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PERFORMANCE SUMMARY

Γ			· · · · ·		ı	T	AFSPP.														
	uion Lite	CAMERA	CERTAL No. 11 EM	M ; P VALUE	NISHAL RES		AVENAGE	Sult (4)		S. 11 (m)	ALL	наўні Наўні	00 % <u>AT</u> PLTCH	TITUDE ERF	YAW	-90% AT	TITUDE RATE	S (VIR)	90 % V/H ERROR (ሂ)	90% RESOLUTIO ALONG 1 RACK	CHOSS TRACK
100	4-1	FWD AFT	124	85	78 56	!	37 60		109 26		115	127	0 4 5	0 42	1 08	30 0	25 0	210	5 I	7.7.	6.1
100	4 - 2	FWD AFT	125	85	76 73	350	88	43	113 106	320	8 2 8 3	90 95	0 74	0 50	0 91	44 0	30 0	29 0	4 9	6.8	6.5
100	6-1	FWD	148	90	73 74		G5 71		88 90		84 87	97 92	0.41	0 42	1 14	26 8	28 5	27 8	15 4	13 8	6.7
100	ii-2	F AD AFT	143	90	35 83	350	64 72	43	8 i 90	320	84 87	90 34	0 49	0 40	I 08	31 [27 9	30 0	11.6	10 1	7.0
133	7-1	FW.U AFT	144/	85	80 86		60 63		87 63		82 57	91	0.58	0 46	1 43	37 6	23.9	29 9	3 6	3 1	9.4
120	7-2	FWD AFT	145	8.5	79 81	350	72	43	81 92	320	68 74	110 74 81	0 64	0 47		43 0	25 8		4.6 3.2 4.2	2 1 2 4 1 8	7.6
100	8 - 1	FWD	150	85	80 76		80 73		95 89		31	89	0 5 9	0.39	0 94	43 8	23 9	29 6	2 9	4.9	5 9
100	0.2	FWO AFT	151	85	82 79	350	84	43	96 83	320	85 83 85	95 92 91	0 63	0.36	071	42 9	24.0	32 5	2.8	4 2	5.4
	3-1	FWD AFT	154	85	92 89	350	80 85			80	75 75	88 83	0 65	0.65	0.71	29 2	22.7	27 6	3 3	5 3	5 8
ļ	3.5	F #C	155	85	94 87		85 87				76 72	84 79	0 48	0 65	0 59	33 6	23.9	27 2	2 6	4 9	5 9
101	0 - 1	F WD AF T	152	85	90 88		90 86		83		87 92	96 103	0 93	0 30	0 87	39.1	23 6	30 8	4.5	2.3	4.4
	0-2	FWD AFT	153	85	92 90	350	81 62	80	82 85	80	82 87	93 96	0.59	0 70	1.21	45 4	23 6	30.7	4.6	7*5	3.8
101	i - I	FWD AFT	160	90	84 84	350	76 77	80	36 86	80	78 83	87 93	0.77	0.39	0 97	43.1	28.9	31.1	2.3	5.3	5 6
	2-1	F WD AF T	156	8,5	92 91		_	80	91 87	80	84 89	98 100	0 65	0.51		47.1	33.2		1.5	4.8	
 	2-2	FWD AFT	157	85	91 89	 .			89 96		84 85	91 98	0.97	0.77	0 51	45.2	30.7	20.4	5.9	3.3	5.9
	3 - I 	FWD AFT	158	85	89 77			60	94 97	80	85 81	99	0 64 0 64	0 32 0 32	1.34 1.34	36 9 36 9	29 0 29 0	32.3 32.3	3 7 4 5	7.8 9.6	8 3 8 2
1	4-1	FWD AFT	162	80	87 83				78 80		74 95	86 107	0.62 0.62	0.41 0.41	1.46 1.44	35 O 34 8	36.1 36.0	33.5 38.3	2.2	€.2	3.8
101	4 - 2	FWD AFT	139	80	83 86			80	75 84	80	70 80	77 88	1.06	0.55 0.59		38.4 38.1	36.4 36.0		3,3 1,4 3,2	2.8 6.4 2.2	6.3
	5-1	FWD AFT	138	85	87 . 87				76 73		90 97		0.65 0.64	0.38	0.53	47.0	29.4	38.2	5.0	5.5	7.8
101	5-2	FWD AFT	141	8.5	83 82			80	72	80	89 90	-	0.50 0.50	0.39 0.61 0.61	0.53 0 64 0.£4	46.9 39.1 39.1	29.2 27.1 27.0	39.2 36.3	6.3 3.2 3.3	3.4 6 8 4.6	5.5 7.5 5.3
101	6-1	FWG AFT	132	85	85 83		,		56 61		81 94		0 72	0.83	2.01	48.9	30.2	40.4	2.0	5.5	10.5
101	G-2	FWD AFT	133	8 5	9C 91			80	55 56	80	92 91	_	0 72 0.83 0.03	0.83 0.93 0.93	2.01 2.19 2.19	48.4 42.2 42.2	30.1 27.2 27.3	40.4 39.5 39.3	2.8 1.5 2.3	3.4 4 9 3 3	7.4 8.0 7.1
101	7-1	FY/D AFT	140/	85	72 75				57 70		78 94	86 107	0 49	0.76	2.50	35.5	32.2	38.4	3.3	9.8	11.6
101	7-2	FWD AFT	165	85	85 85			80	65 69	80	80 86	94	0 49 0.69 0 59	0.76 0.45 0.45	2 49	35.3 36.5 36.3	32 0 34.0 33 8	38.5	4.3 1.8 2.3	8.3 6.2 5.3	8.1
10:	8 - 1	FWJ AFT	122	65	79 77			,	70		82	92	0.91	0.48		47.4	36.7		3.4	5.6	
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EC / 10H

PERFORMANCE SUMMARY

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			12 a pr	مدد و د				int interviol	5, 11			AI	137 · 179	(74 (*) <u> </u>	1 1 AI	11 (1 - 42) 1 - 40)	S (mat)	90% VVH C8 60%Us	GOT, RESTRICT	10.007 (0.07) CAUCA TSACK
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10.0-2	1 444 2 444 4 447	36/	۵٥ -	20 25 			80	62 62 —	60	76 94 —	(U 105	0 40 6 41 C 41	0.35 0.35 0.17 0.17	0.73 0.73 1.06	37.4 37.4 42.6 42.6	31 3 31.3 23.3 23.8	26.7 26.7 42.5 42.5	5 . 4 5 . 3 3 . 5 3 . 4	5 9 4 2 6 4 4 5	0 + 5.5 7.0 2.9
1021-1	7.43 - 47.7 - 48.7	/167	65 65	6d 50 65 74		_	60	77 90 74 62	80	33 94 95 —	69 109 112	0.55	0.37 0.33 6.66	0.81	34 9 34 8 44 7	32.6 53.0 50.6	26.2 26.3	2.7 5.4 3.1	8.6 5.6 9.2	8.3 5.5
1022 - 1	13 Ar 1 13	160 /	υ ό δ.,	52 52			ćO	53 53 66 92	60	76 101 -76 93	91 11. 54 110	0 47 0 47 0 40 0.40	0 5 1 0 5 1 0 5 1 0 5 1	0 89 0 95 0 98 0.90	28.5 27.9 29.4 29.4	27.4 26.6 27.3 27.3	23.6 23.6 31.0 31.1	3.5 3.0 2.6 1.8	9 8 6 C 8 C 4 9	S 6 6.1 8.4 5.9
10.33 - 1	#W3 #17 #47 #47	170 /	65			_		94 97 71 90	80	57 63 76 68	110 101 57 75	0.49 0.45 0.43	0.33 0.33 0.35 0.37	0.50 0u 0.55 0.53	33.0 33.9 29.7 29.6	23.7 20.7 21.0 21.3	23.5 23.6 23.6 23.6	3.4 3.5 2.4 2.5	4.0 2.7 3.5 2.7	6.4 4.5 5.3 4.2
1024+1 1024+2	7 40 AFT 7 WO 1 AFT	172 /	65 61			_	υO	77 55 60 95	ยอ	90 94 69	102 105 101	5 42 6 42 0 36 0 20	6.25 0.25 0.31 0.31	0,62 6,62 0,93 0,93	32.2 32.2 30.4 30.6	24.9 24.9 24.5 23.6	30.5 30.4 35.4 35.4	2.0 2.1 5.5 5.1	5.9 3.6 4.7 3.3	6 û 4.5 5 4 3.6
1025-1	##.2 ##.7 ##.0 ##.1	142	U.S U.S			_	دة	67 97 85	8·)	101 101 93	97 116 107 103	0.50 0.51 0.52 0.53	0.41 .0.42 0.44 0.44	0.35 0.85 0.62 0.62	28 1 25 6 25.0 28.1	26.7 29.7 26.1 26.0	25 9 25 7 29 0 29 0	2 0 3 2 1 7	3 5 2 3 4 7 6 7	6.7 0.6 6.9 0.9
1025+1	7 W.5 7 W.5 7 W.5 6 Y.5	174 175	ა\$ 85	_	-	_	90	76 88 85 93	80	- 40 98 92 90	52 113 104 103	0.65 0.55 0.55 0.59	0.24 0.24 0.55 0.65	0 70 0 70 0 87 0 88	37.9 37.9 41.1 43.3	33.2 33.2 46.5 50.0	28.5 28.5 30.8 27.7	6 : 6 : 6 : 6 :7	13 5 9.1 5 5 3 5	0.2 4.1 6.7 4.5
1527+1	FW3 AFT	16:103	Ü 5				80	69 73	60	80 80		0.51 0.51	0.37	0 74	47.2 47.3	25.5 25.2	26.4 26.2	4.7	10.5	7.2
1028-1	AFT FWD AFT	176 177	65 65	-			80	61 92 88 77	90	89 93 87 84	<u>-</u>	0.53 0.52 0.76 0.76	0.37 0.37 0.52 0.52	0.50 0.50	36.6 36.6 42.7 42.5	28.0 28.0 25.7 25.6	30.5 30.5	3.9 3.4 3.2 2.9	4.8 4.0 4.2 3.3	ช . O 5 . u
1029 - 1	FAO AFT FWO AFT	178	65 65		80	100 100 11 11 11 11 11 11 11 11 11 11 11	60	95 02 94	60	77 73 77 81		0.07 C 68 0.64 0.65	0.34 6.33 0.48 0.48	0.77 0.77 0.44 0.44	29.1 28.5 38.6 37.5	31.3 30.8 32.5 32.1	34.4 34.6 25.7 25.7	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	7.6 3.5 7.5 2.9	7.4 4.2 7.5 4.9
1030 - 1	FWD AFT FVD AFT	183	85 85		86	95 74 77 91	80	76 79 81 74	80	66 77 71 71		0.67 0.67 0.70 0.70	0.25 0.25 0.27 0.26	0.35 0.39 0.67 0.67	29 6 29 6 26 4 28 2	22.7 22.0 21.7 21.9	36 1 35.9 36.3 56.3	3.9 5.4 4.9 5.6	0.9 5 1 1:.2 0.6	8.0 5.6 9.6 5.5
1031 - 1	FWD AFT FWD AFT	164	65 85		80	65 57 91	60	76 71 94	80	66 74		0.50 0.54 0.57	0.47 0.41 0.20	0 98 0.31 0.75	16.2 18.1 19.0	17.3 18.7 19.3	26.0 22.6 15.7	6.1 6.0 5.4	13.8 12.0 10.3	5.4 5.0 4.9
1033 - 1	FWD AFT FWD 4FT	194	85 35		60	77 67 75 93	80	94 93 90 92	60	67 72 90 73		0.11 0.15 0.21 0.20	0.33 0.27 0.24 0.24	0.80 0.59 1.09 1.06	11.3 8.2 22.3 22.3	34 9 55.6 49.3 50.7	27.3 19.5 17.5 17.4	3.5 4.9 2.0 2.9	5.2 e.i 5.6 7.3	0.2 5.0 0.0 6.7

H. C / . OM 12/65 AOF BECREAT C

PERFORNANCE SUMMARY

<u> :</u>	of many											TUDE WATE		96 & V/n	1 7	N FORETHELD)	143
-		CA3. 34	landa Maria	Maria Maria	AVEN A	5. 17 f. o l	i		1.700L 2000	YAW	2:704	1.76.6	7. 1.	ERRUR (%)	ALONG THACK	CROSS THACK	ERACK
						 -		6.30	5	<i>0</i> 59	13.3	20 4	24.0	15.0	17.6	5 5	
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	5/4 - 2	1555 1577	131	63	14 6	1	ر خ د ن	0 34 0 34	0.30	. 35	21.1	25 6	15 2	F 9	8 0	5 3	
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		133		£ ,				3 76	9 93	6.0	31.2	25.6	29.5 29.4	3.4	3 8	68 51	
	, ,		173/		73	50	_	0.76 0.94	5 95 6.70	0 (i) 0.40	31 .	25.5	23.3	3.3	3 6	6.5	
i .,	0,6-2	1 45 43 T	المناف محمرا	LS	b-i	1	l	0.54	0.76	0.45	30.9	23.7	23.3		2.7		
	537	F.75	10L /	65				65	0:0	1.50 51	22.7	42 0 35 9	29.3 32.4	9 5 16.1	, C :	3. 0	0 3
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i			207				<u> </u>	3.3	0.53	2.52	27.1	24.2	25.9	2.6	3.9	2.6	5 0 2 e
	٠4٥٠١	6%0 467	106	85	54 69	i 	1	5.53 0.35	0.50	2.99 3.00	26.6	23 2	28.4	2.1	1.29	2.5	2 1
1.	340-2	FWD	·/ 197	ชร์	6.1	80		0.52	0.49	2.56	27.5	30.0	32.5	1.6	2 2 5	20	1.7
ļ	·	^= T	1/			<u> </u>		0.39	0.46 0.16	2.56 3.05	27.2	26.4 14.0	12.7	5.1	6.4	3 4	2.6
1	341-1	FWD	25a /	85	72 82			0.35	0.16	3.05	i 5.8	13.5	13.0	5.8	5.7	3.0	5 7
1	741-2	FWO	209	85	73	60	1 —	0.28	0.23	2.94 3.01	22 9	15.7	19 8	4.5 5.6	5 4	2.1	4 9
ļ <u>-</u>		AFT_			73	İ		0.3:	0 22	2.66	22.1	36.3	27.0	3.1	3.3	1.5	3.1-
'	342-1	FWD AFT	204	Ú 5	85	30		0.32	0.24	2.83	23.4	33.0	25.9	3.2	2.7	1 1 1	3 4
1 1	O42-2	FWO	205	85	70	80		0.31	0.38	2.39	16.1	46.1 33.6	31.4 25.6	2.1	2.5	2 2	2 3 2 U
ļ		AFT	/		74	<u></u>	-	0.32	0.23	3.11	23 9	22.0	41.5	4.2	5.4		4.2
j '	043 - 1	FWD	200	85	67	60	l	0.31	0.23	3.14	25.4	20.5	34.0	3.3	2.8	- 00	3.3
1	043 - 2	7.95	201	35	65	60 	!	0.30	0.34	2.73 2.78	29.2 27.3	29.9	47.9 45.1	4.3	5.3	0.9	3.2
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	101-2	FWD	1/	!			"		1		1						
		AFT FW3	Y	 	76		 -	0.30	0.15	5.42	14.C	26.2	51.3	4.2	7.6	9.6	4.0
		AFT	202	65	71	80		0.30	0.16 0.37	3.36 3.31	16.1	24.2 30.6	42.7	3.0	4 4	6 4	3 2
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EXPOSURE-PROCESSING SUMMARY

Control Cont			5.1	.AR	571	A 4.	Pil	3767	151	Fife	ATED	E SOM	TUTE:	<u> </u>							т					·					
Control Cont			ELEV	إ بري. ت.	4711	يهجرو	CHO	(555)				PROCI	5551N	rs		N D	NIN			0-4/	14			D - MA	X				OVER		CLOUD
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SUMMARY

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SECTION A

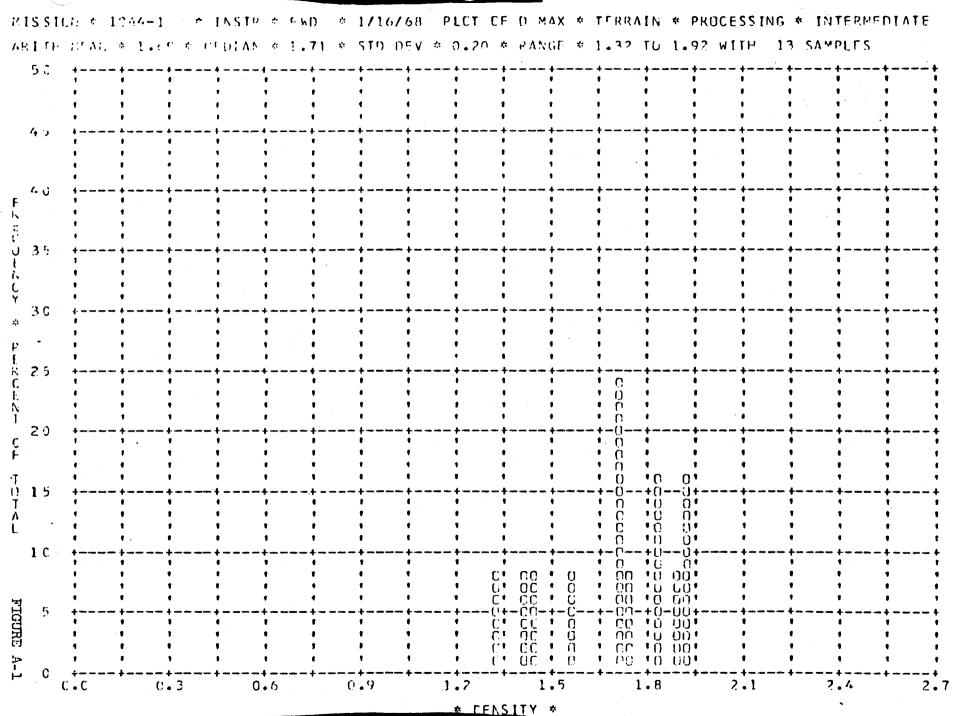
APPENDIX

* CENSITY *

2.1

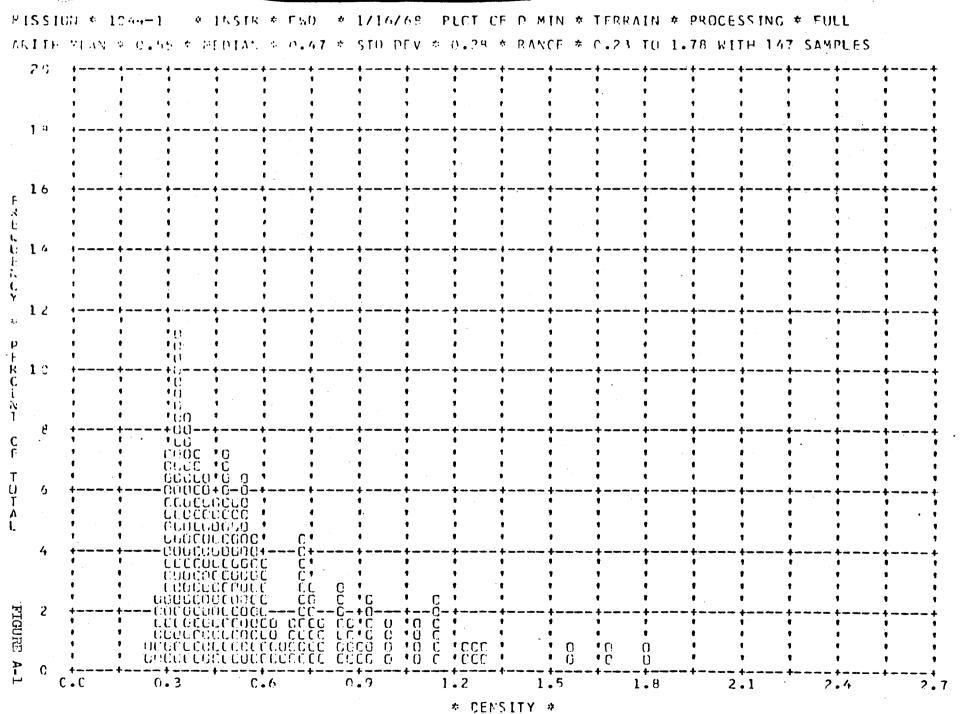
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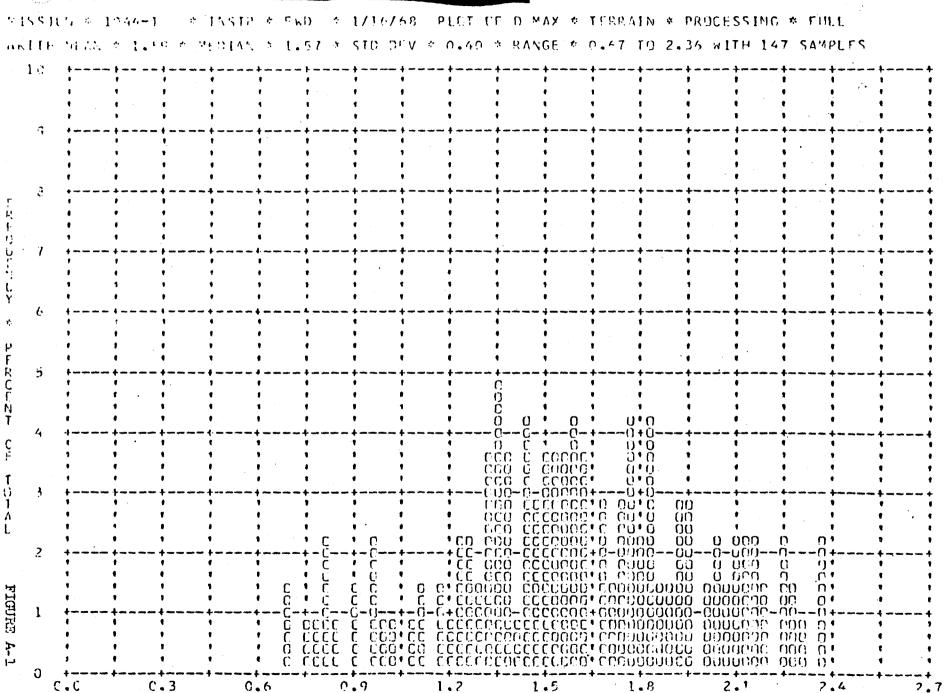
2.7

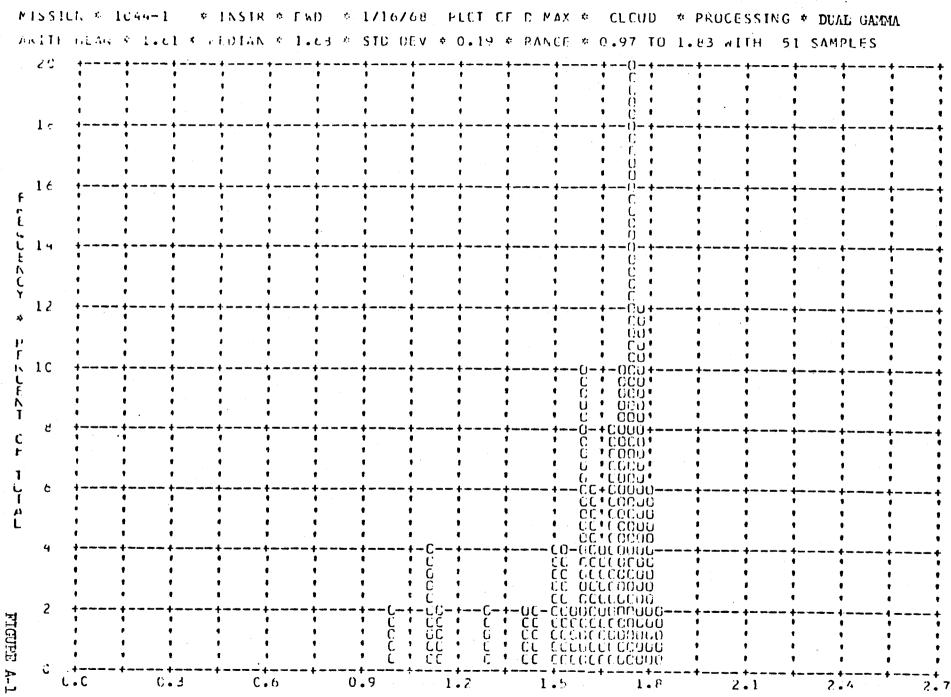


MISSIN # 1044-1 # INSTR # END # 1/16/68 PLCT OF D MAX # CLOUD # PROCESSING # INTERMEDIATE ARITE HEAR & 2.07 & MEDIAN & 2.09 & STD DEV & 2.25 & RANGE # 1.58 TO 2.44 WITH 13 SAMPLES 1 16 0 0 • 14 n. n. ŋ • n. 111 12 0 1 **n**• n · n. R 10 O . 7 (11 n. Ò٠ () 1 יח פיטים ก ก Õ 0 0O ים כים Ω 0.0 ö : O O O U U O O ! n• n 0 0 Ó 0 0 0 0 () · () 0 . 0000 \mathbf{u} 0 $0 \cdot 0$ O 1 0 0 0 0 0 ր ը։ 0 1 0 U 0 0U 00000 $0 \cdot 0$ 0 • U O U. יח פיט ט 0, 0 - () + - ()-0 * $\mathbf{C} = \mathbf{O}$ 0 0 0.0.0 0 0 Û. $0 \ 0$ 0 0 0 0 n • n Ò Üυ ים מ מ מ ח יח 0 1 חי ה $\mathbf{0}$ U () N () • FIGURE 0 • U U Ō 0 0 0 0 0 11 0 Ö U O U ים ר מ ט חיים 0 : 0.0 0 0 0 00000 O O 0000 **n**• n 1.2 1.5 0.0 (.3 0.6 0.9 . 1.8 2.1 2.4 2.7 * CENSITY *

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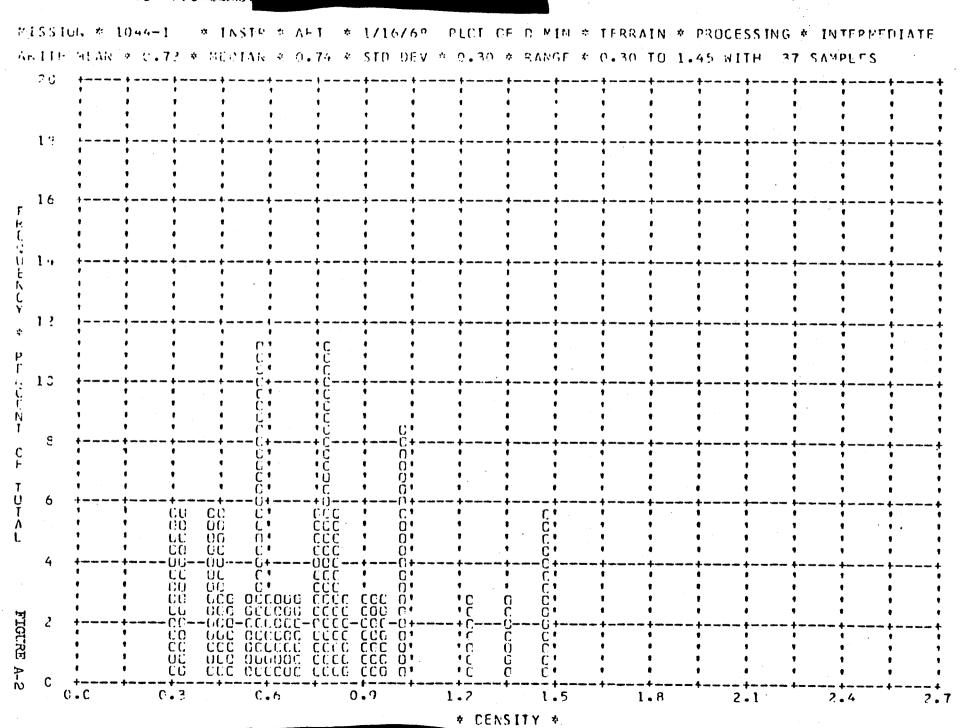




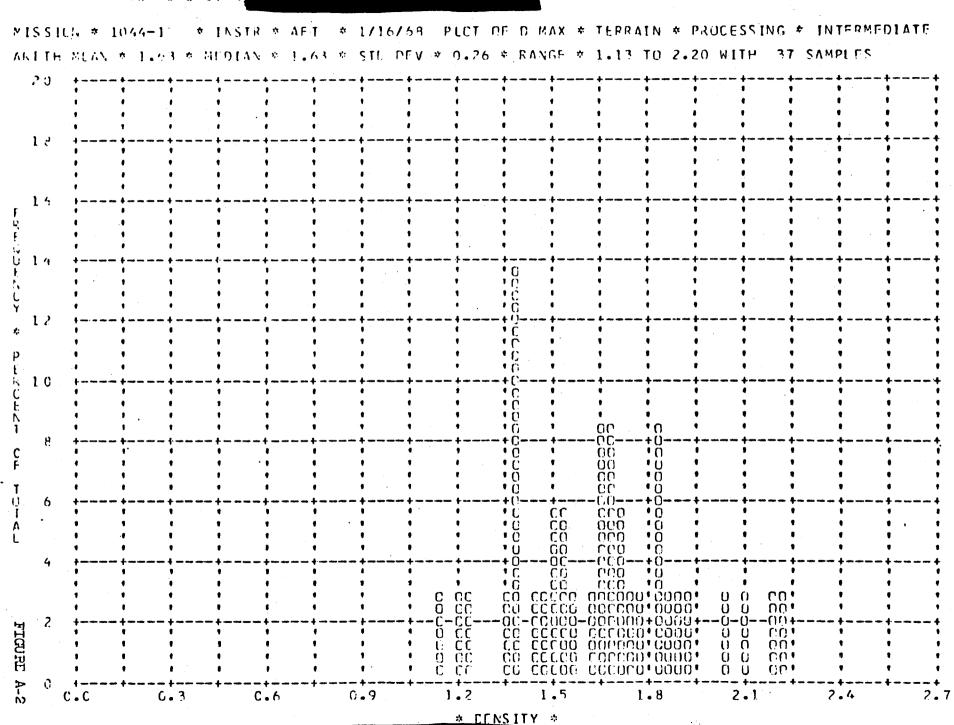


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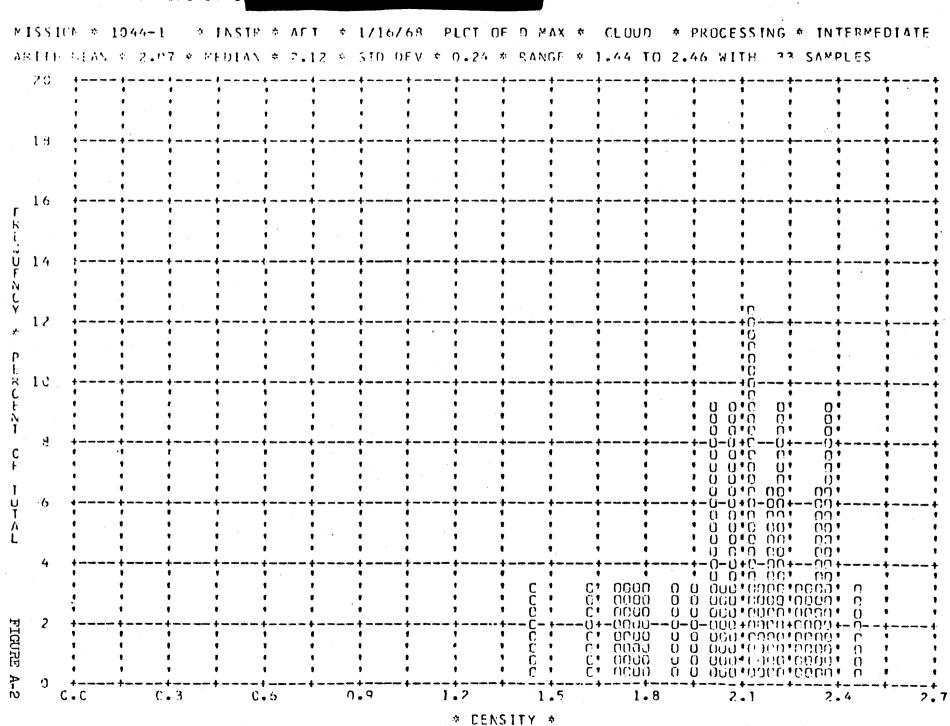
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MISSIUN # 1844-1 # INSTR # AFT # 1/16/68 PLCT OF DIMIN # TERRAIN # PROCESSING # ALL LEVELS ARITH NUVY & 1.50 % SUDIAN & 0.53 % STO DEV # 0.25 # BANGE # 0.27 TO 1.45 WITH 163 SAMPLES 10 t. (: *t. C *0 0 rc *U (*UU) *i. Lilili 16 (66.6 +1-(1('')()-(+to Ebbed Ct *U USCCO C* CLUCCICLOCK! 0.00000000000 C addendecede GCCCCCCCCCCCC G annacetacet co co 00000000000000000 CHUCCHELBOOLLC CULCULCULLULU CCC UCOCOULCCCLLAR-UCC COUNCIDE COUNCIDE COC 00 * ČC* COURSELECTION €G • 60000000000ccC0-00 *ccc a GO * ינונה מ ינונה מ CC * 1000 0 C.C 0.3 0.9 1.2 1.5 1.8

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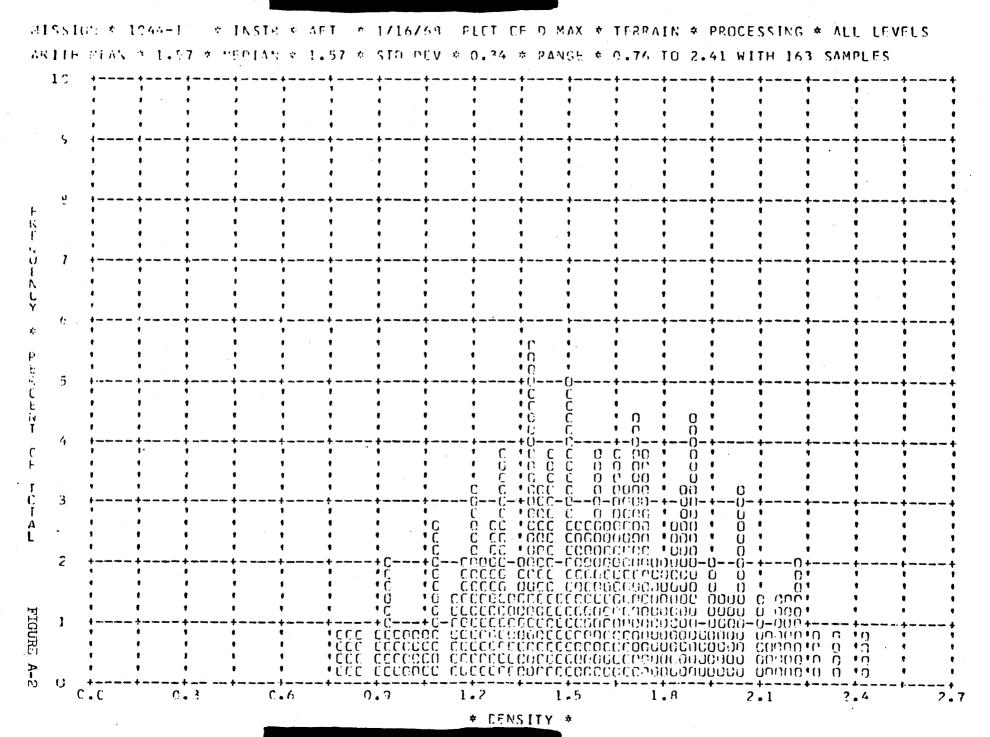
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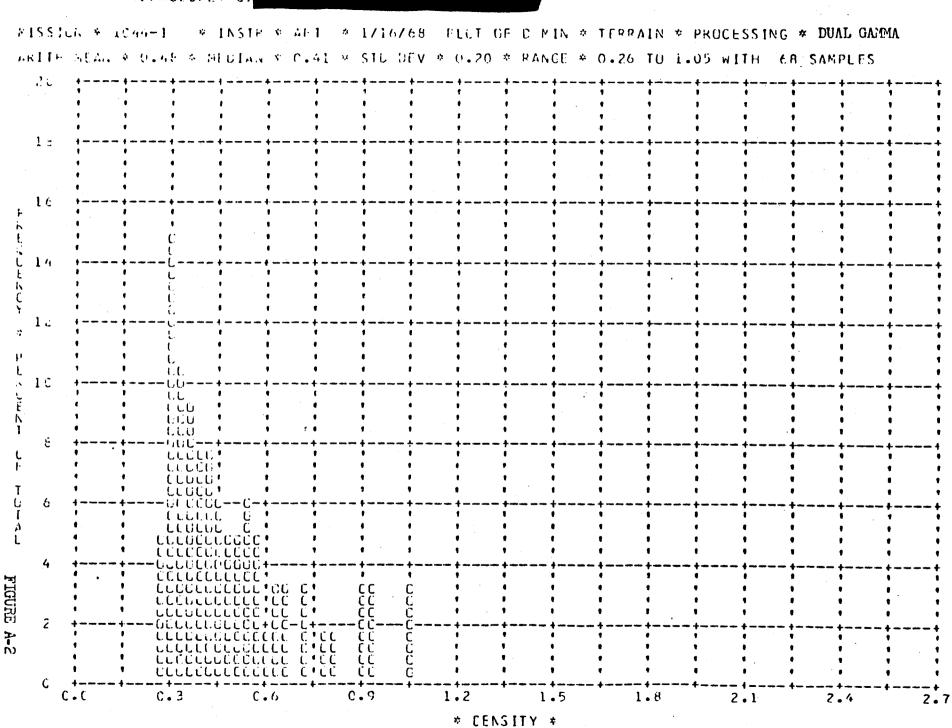
TUP-SLERET



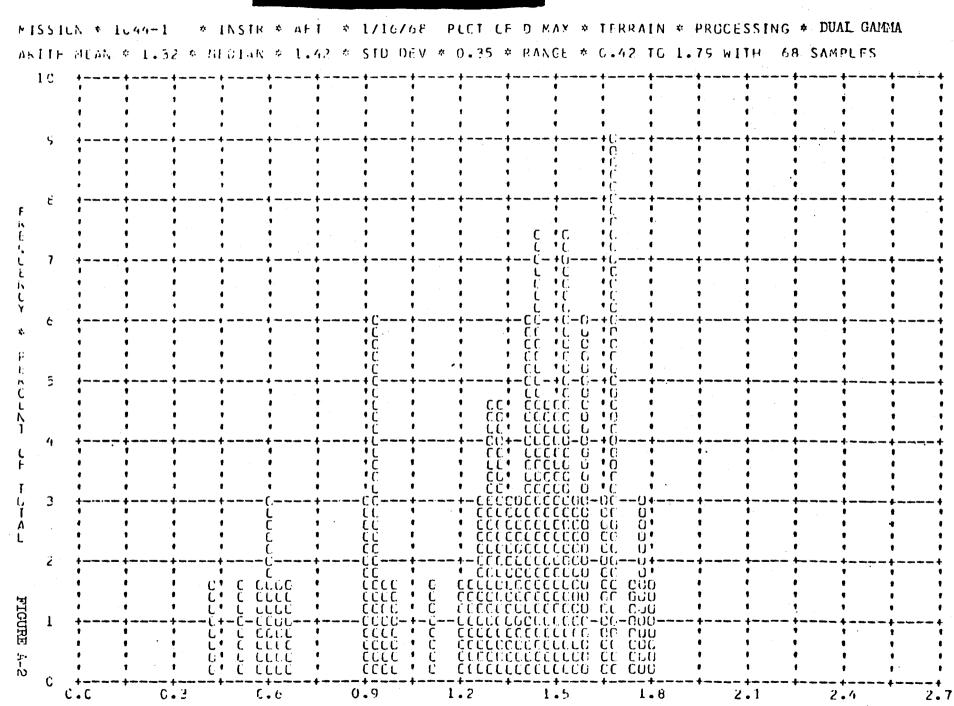
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TOP SECRET



THE SECRET C



* CENSITY *

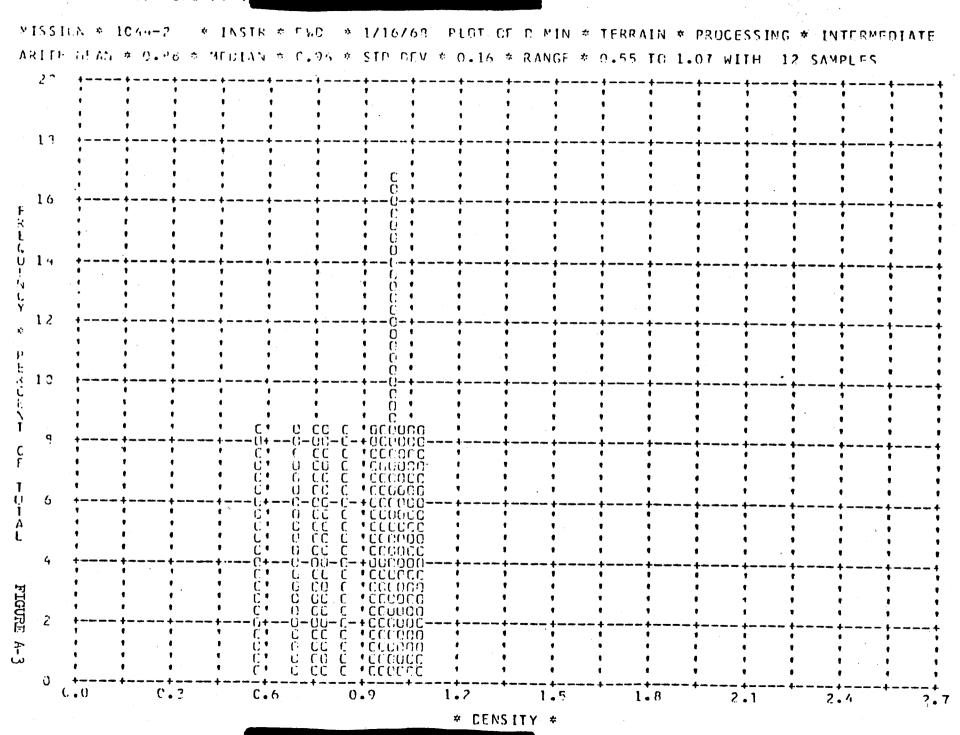
MISSIUM + 1044-1 * # 1851R # AFT # 1/16/68

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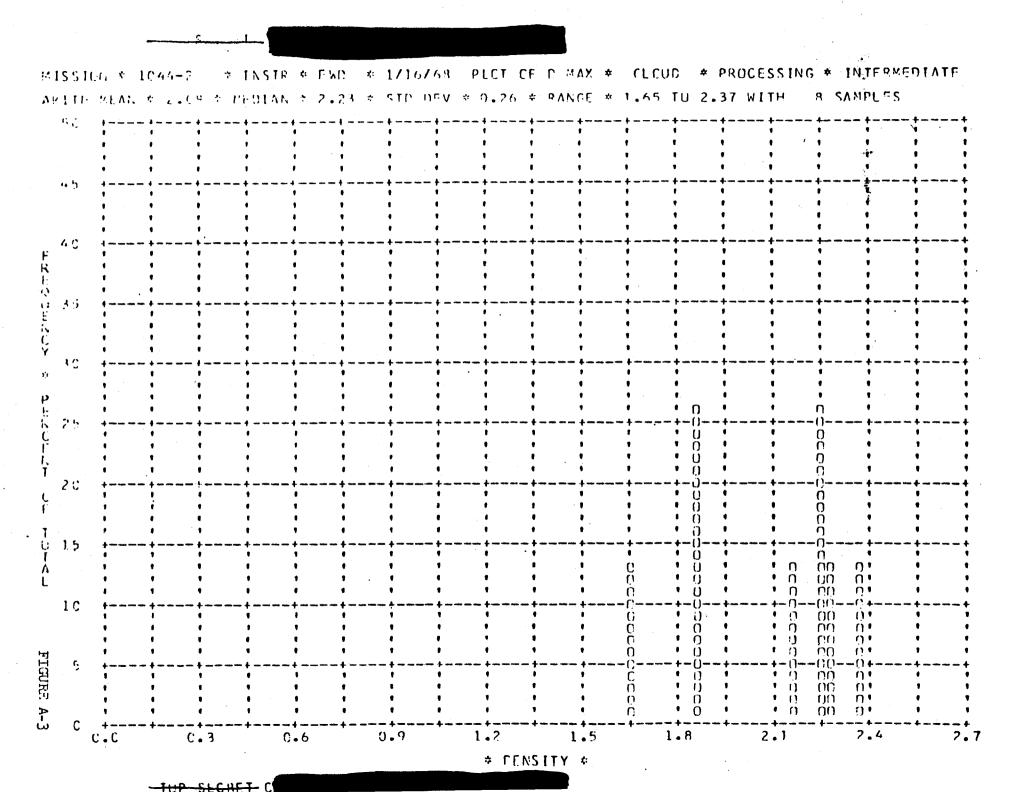
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-TUP SECRET C

MISSION # 1044-2 - # INSTR # FRD # 1/16/69 PLOT OF D MAX # TERRAIN # PRUCESSING # INTERMEDIATE ARITH SEAS # 1.77 * MEDIAN # 1.77 * STO DEV # 0.10 * RANGE # 1.51 TO 2.19 WITH 12 SAMPLES 13 00 OO 16 UU 00 110 60170 -00 1 4 UÜ 00ua UC 12 -00 00 :00 OU. UÜ 13 ÜŪ un 00 io ocio não o +()-()()+()-()()-()--+--()-+--Ď dão á tiú á t U . 10 001 3130 01 10 000 0100 0 n 0 io octo nob o +0-00+0-000-0-ם הניט מישמ חי *G 00*0 000 0 U n *6 00*6 000 0 0 • *U 00*C 000 U 0 1 n +0-00+0-000-0-10 000 0100 01 0 000 0100 01 FIGURE 10 0016 000 0 *C 00*6 000 0 10 0010 000 0 0 1 () · 16 6616 000 0 A-3 10 0010 000 0 0 10 0010 000 01 0.0 1.2 1.5 2.4 0.3 0.9 1.8 2.1 C.6 2.7 * CENSITY *



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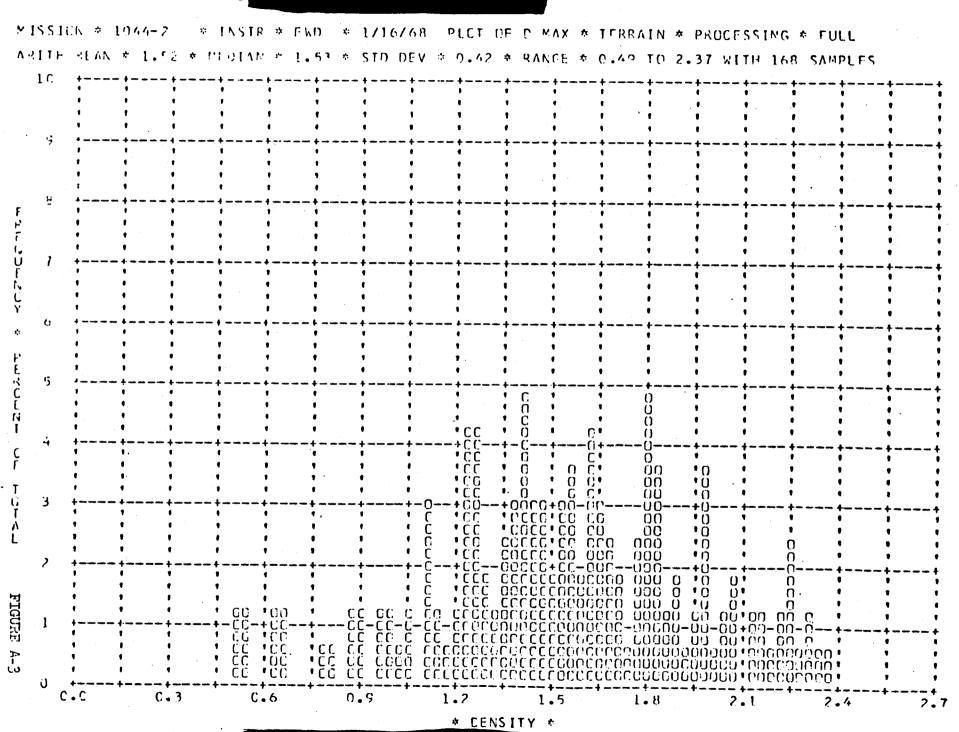
2.4

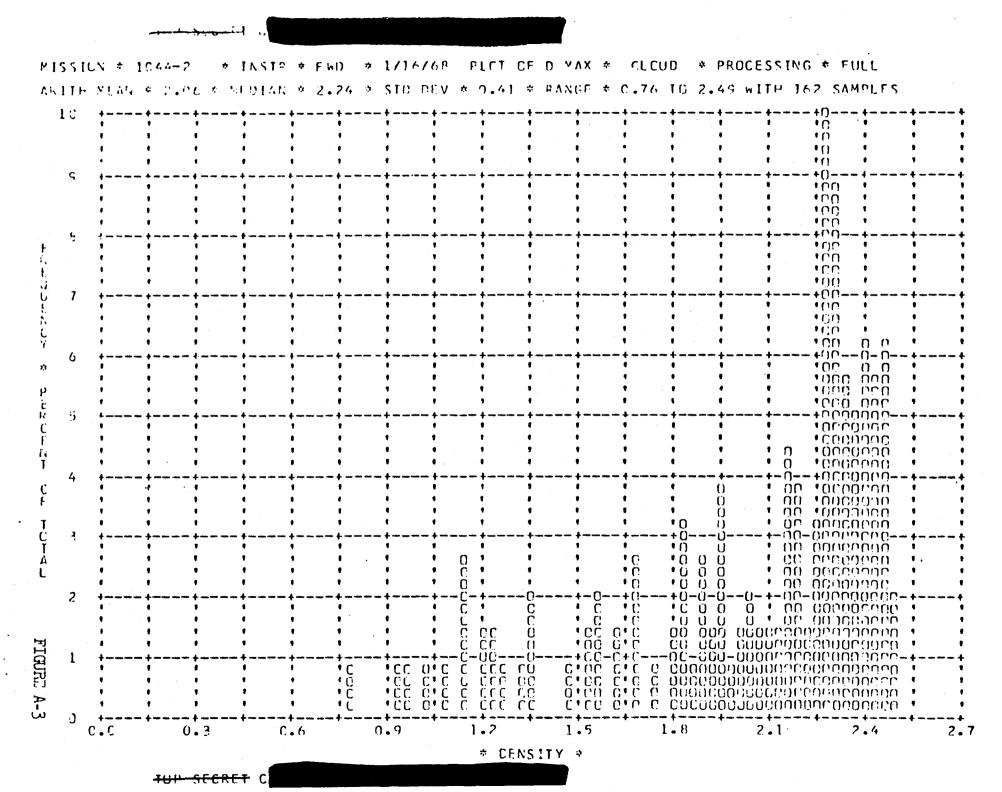
2.7

* ISSICN # 1044-2 | # INSIR # END # 1/16/68 | PLOT OF D MIN # TERRAIN # PROCESSING # FULL ARITH VEAU # 0.50 # MEDIAN # 0.47 # SID DEV # 0.21 # RANGE # 0.20 TO 1.32 WITH 168 SAMPLES

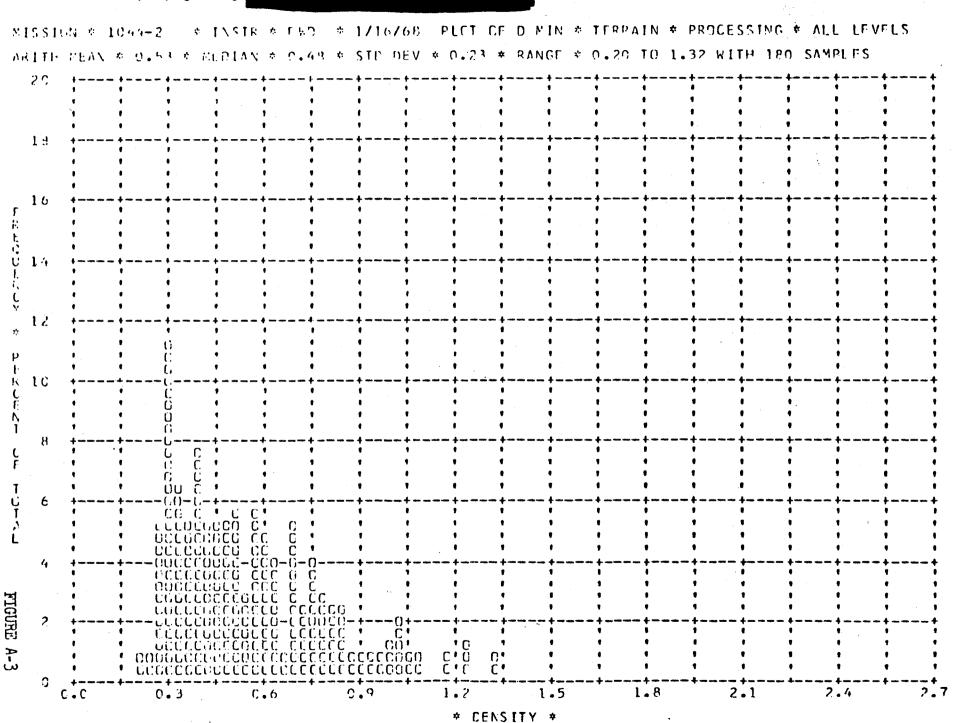
A-2

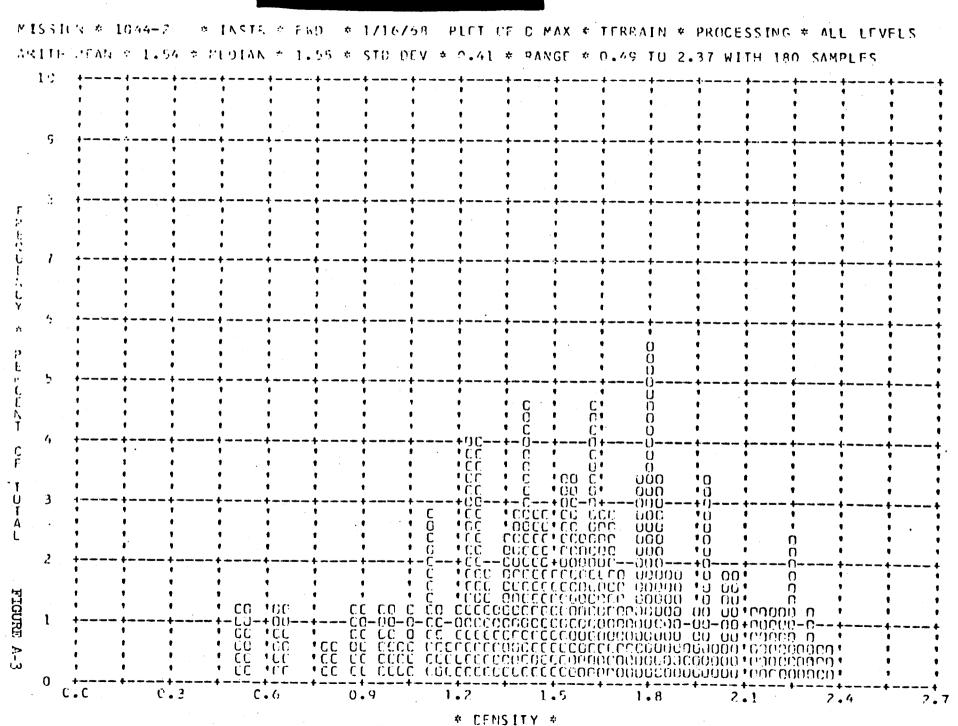
20





TOP SECRET.





* CENSITY *

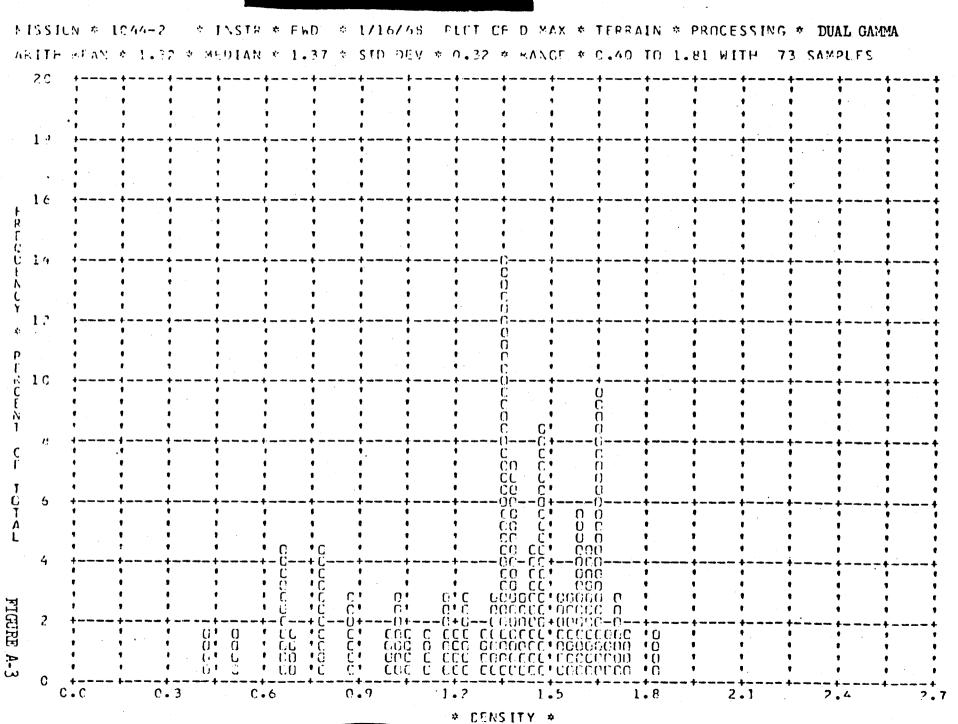
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MISSILM # 1044-2

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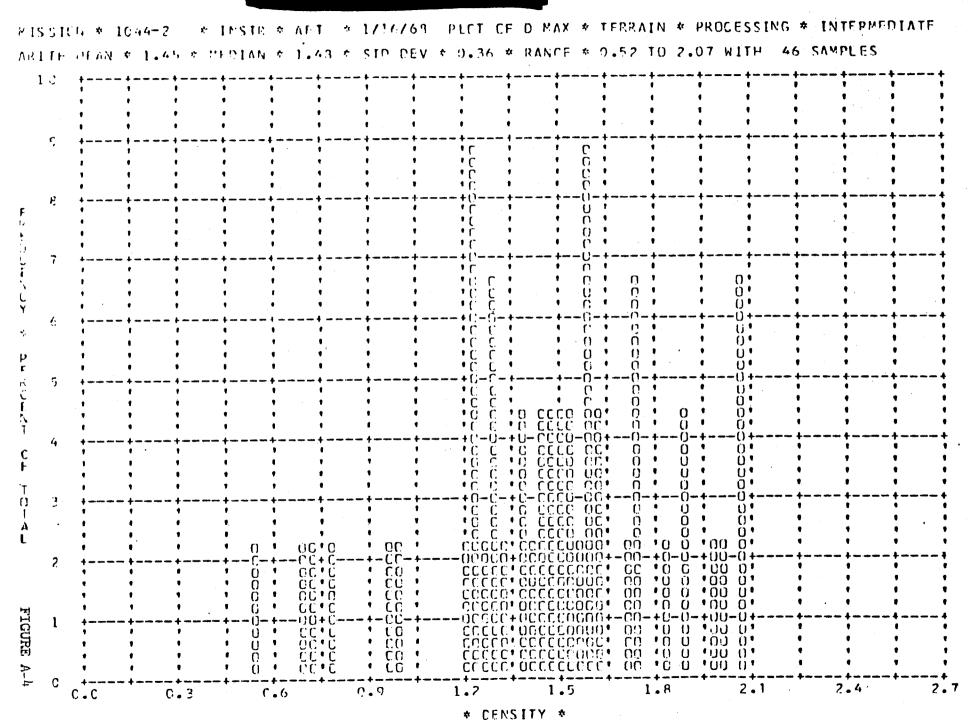
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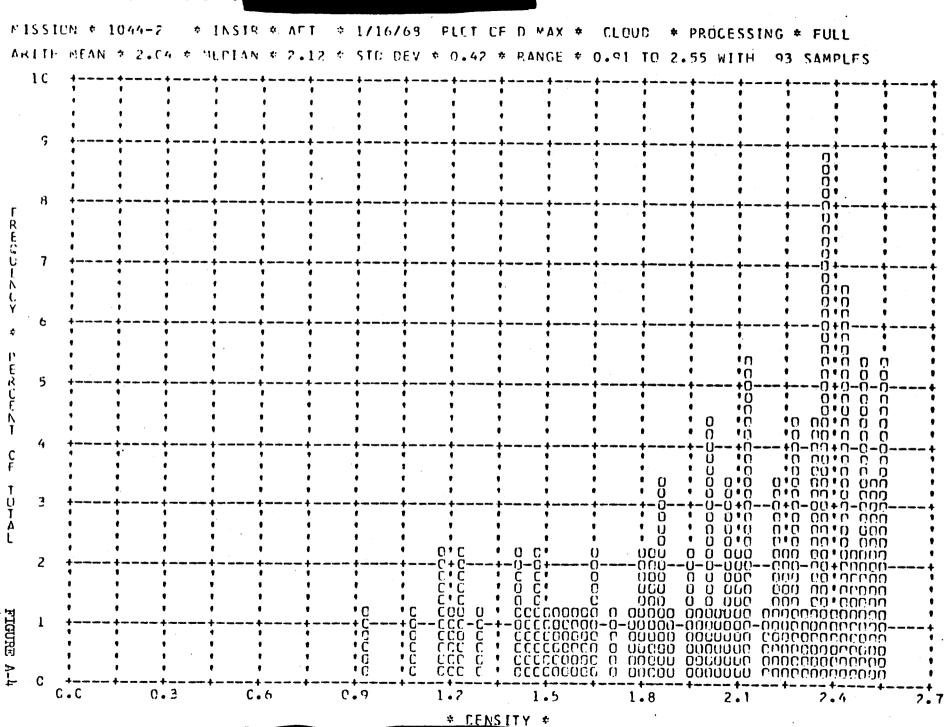


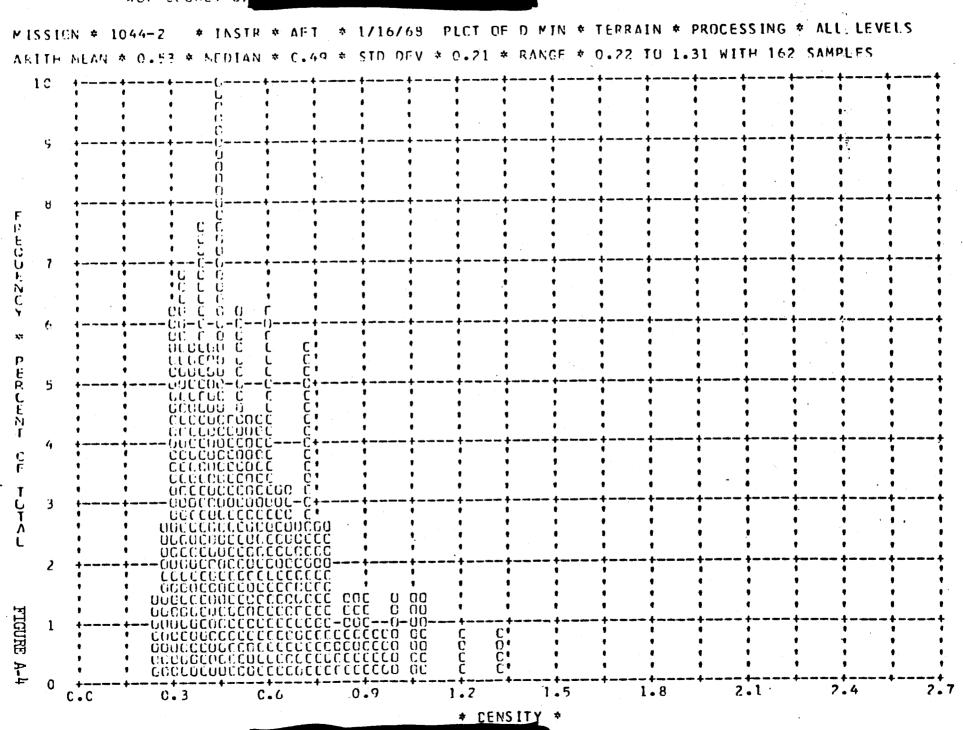
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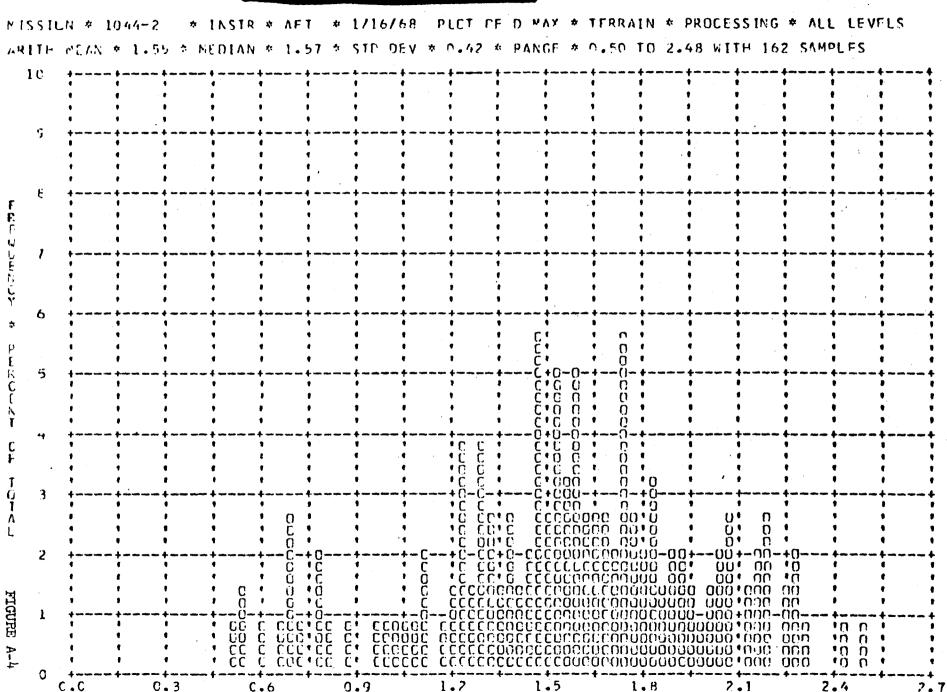
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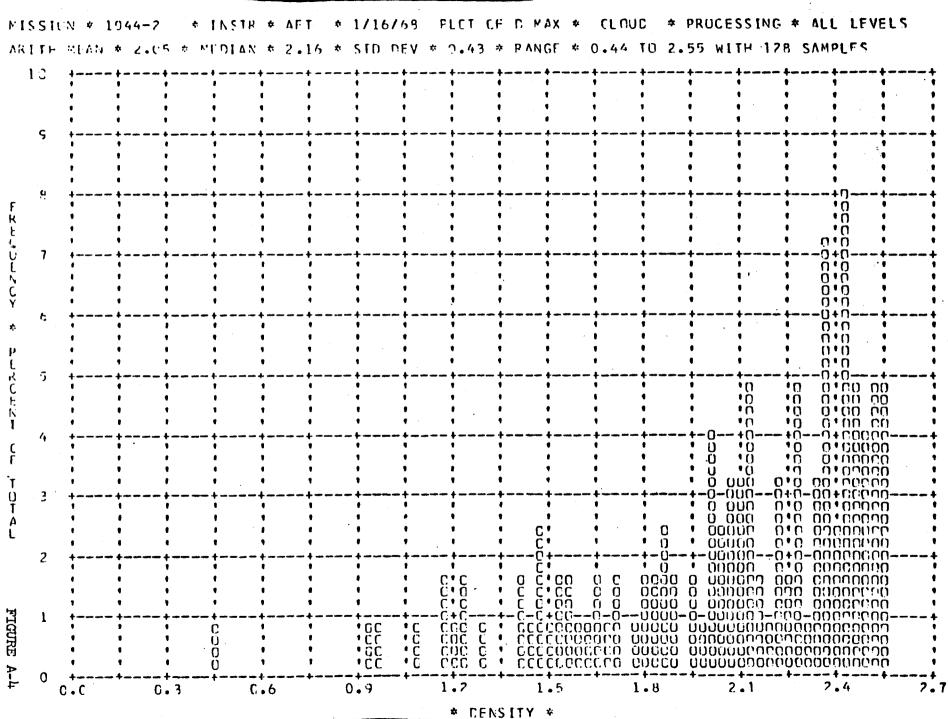
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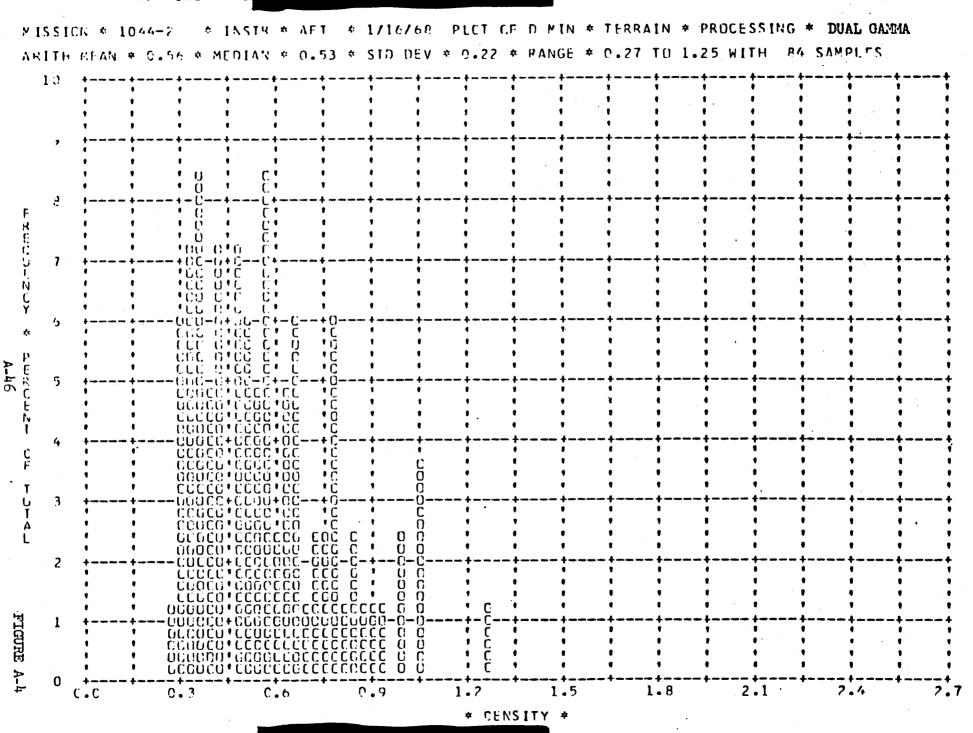
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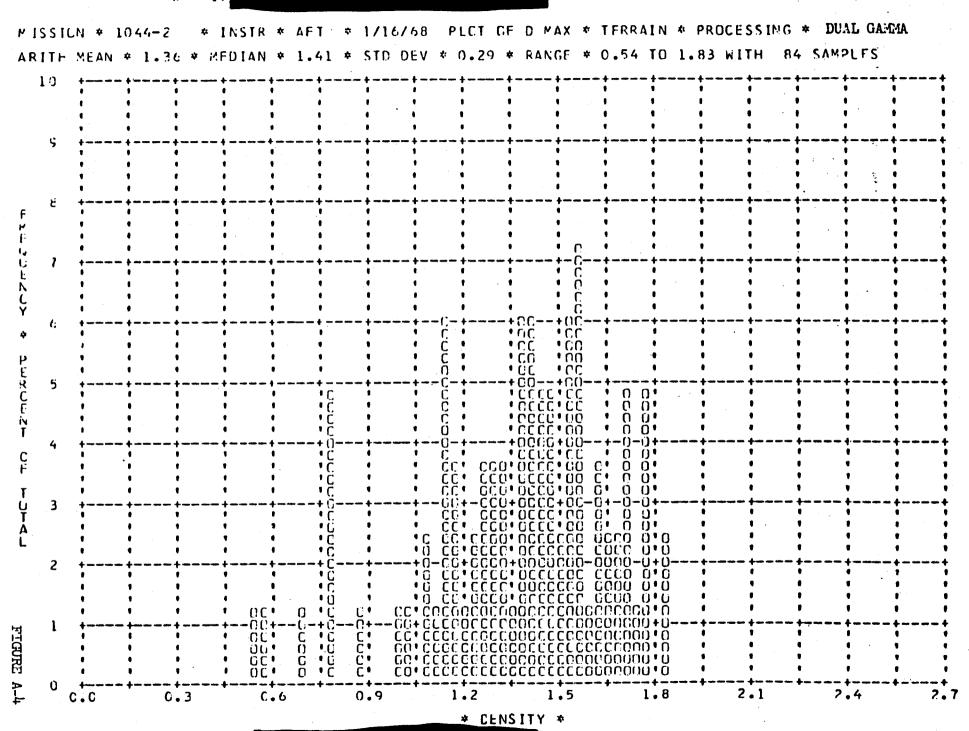


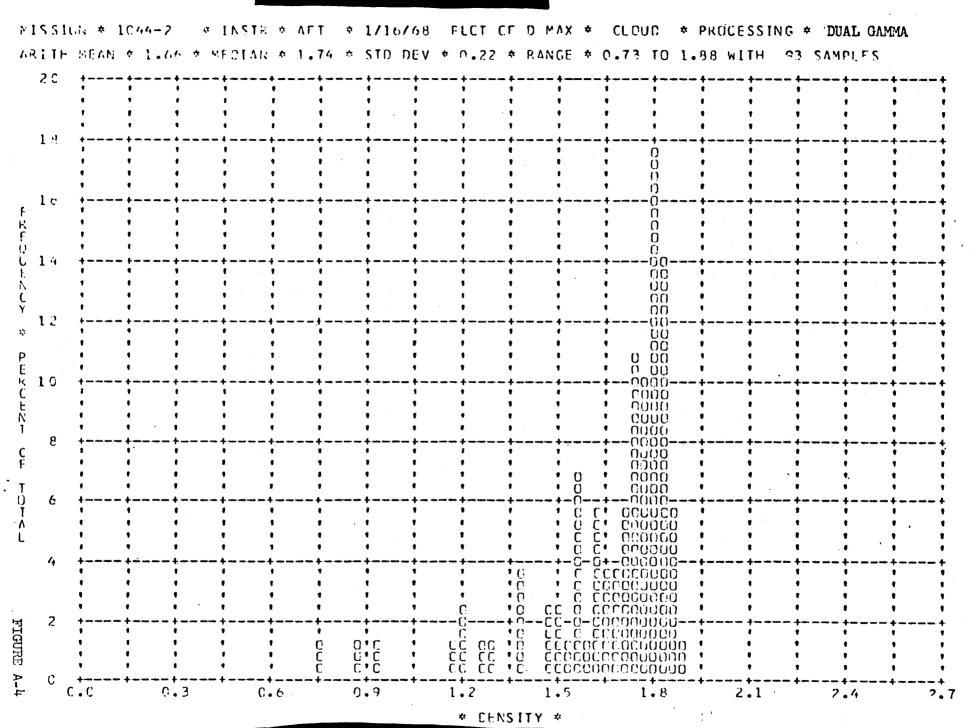












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